



simactive  
HIGH-END PHOTOGRAMMETRY SOFTWARE

# CORRELATOR3D™

## User Manual

Version 10.0

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# 1

# IMPORTANT NOTES



This symbol indicates an important notice. Failing to follow the notice could lead to unexpected or incorrect results.



This symbol indicates a tip or helpful information. Following this advice will lead to better results and performance.

This manual uses the following abbreviations as summarized in Table 1:

Abbreviation	Definition
DEM	Digital Elevation Model
DSM	Digital Surface Model
DTM	Digital Terrain Model
GSD	Ground Sampling Distance
LUT	Look-Up Table
EO	Exterior Orientation
GCP	Ground Control Points
RPC	Rational Polynomial Coefficient

Table 1: Abbreviations.

# 2

## OVERVIEW

Correlator3D™ software is a patented end-to-end photogrammetry solution for the generation of high-quality geospatial data from satellite and aerial imagery, including UAVs. It builds on unique computer vision algorithms that significantly differ from traditional photogrammetry techniques. Powered by GPU technology and multi-core CPUs, Correlator3D™ ensures matchless processing power to support rapid production of large datasets.

Correlator3D™ consists of the following modules:

- **Aerial Triangulation:** exterior orientation correction and camera calibration
- **DSM Generation:** generation of digital surface models and point clouds
- **DTM Extraction:** extraction of digital terrain models
- **DEM Editing:** manual editing of DEMs
- **Orthorectification:** creation of orthophotos and true orthos
- **Mosaic Creation:** stitching orthophotos together creating a mosaic
- **Mosaic Editing:** manual editing of mosaic seamlines
- **3D Model Generation:** generation of textured 3D models
- **Feature Extraction:** semi-automated collection of 3D features

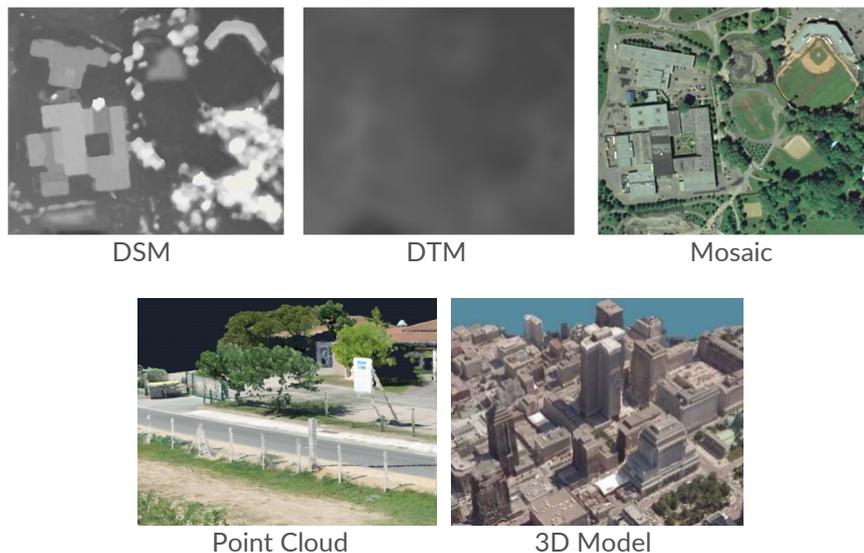


Figure 1: Sample geospatial data.

The software also provides other tools including:

- **Automated Workflow:** automatic execution of Correlator3D™ workflow
- **Data Sharing:** upload and share results using Cesium
- **Flight Line Editing:** remove images from project and modify flight lines
- **GCP File Creation:** semi-automatic tool for creating and editing GCPs
- **Index Map Creation:** computation of predefined or custom indices
- **Change Detection:** identification of 3D changes
- **DEM Merging:** stitching of DEM patches

- **DEM Inspection:** generation of statistics about DEM quality
- **Point Cloud Filtering:** filtering based on the number of observations
- **Point Cloud Colorization:** colorization of a point cloud using a mosaic
- **DEM Contour Extraction:** extraction of contour lines from a DEM
- **Volume Calculation:** measure a volume from a DEM

The following sections describe, in detail, the different functionalities, uses, and guidelines of the software, to ensure optimal results.

# 3

## SYSTEM REQUIREMENTS

Correlator3D™ has been designed to operate on standard PCs. However, it consists of state-of-the-art software and as such, requires a recent computer. A great portion of the processing is performed directly on the graphics card, which is part of what allows Correlator3D™ to generate geospatial data so rapidly. The supported cards must feature an NVIDIA, AMD or Intel graphics processor that is OpenCL-enabled.

Processing can also be performed on a PC that does not have a GPU, as long as the CPU is OpenCL-enabled. However, the corresponding drivers may need to be installed, and the performance will be significantly reduced.

It is therefore recommended to use Correlator3D™ on a PC that meets or exceeds the specifications in Table 2:

Component	Description
<b>CPU</b>	Intel® Core™ i5 processor or higher
<b>GPU</b>	Graphics card with an NVIDIA® GeForce 9 GPU (G92) or higher, with 1GB RAM or higher (note that most Quadro, Tesla, and Tegra cards also feature a GeForce GPU), or with an AMD Radeon™ R9 GPU or higher, with 1GB RAM or higher.
<b>RAM</b>	8GB or higher
<b>OS</b>	Windows 7, 8 and 10. Correlator3D™ is a 64-bit application.

Table 2: Recommended specifications for running Correlator3D™.

# 4

## DATA REQUIREMENTS

Correlator3D™ requires different types of data to be able to perform its processing and can produce several kinds of outputs. As a result, it expects and generates data using specific data types. Table 3 summarizes the supported file formats.

Data Type	Supported Formats	File Extensions
<b>DEM</b>	SimActive Model Format (SAMF) GeoTIFF Arc/Info ASCII Grid	.smf2, .smf .tif .asc
<b>3D Constraint</b>	ESRI Shapefile Microstation DGN	.shp .dgn
<b>Image Types</b>	TIFF / BigTIFF / GeoTIFF JPEG Compliant JPEG2000 Windows Bitmap NITF IIQ	.tif .jpg .jp2 .bmp .netf .iiq
<b>Mosaic Definition File</b>	SimActive Format	.sbd
<b>Tile Definition</b>	SimActive Format	.tdf
<b>Ground Control Points</b>	SimActive Format	.gcp
<b>Orthorectified Images</b>	GeoTIFF (BigTIFF) TIFF (BigTIFF) World Format	.tif, .tif, .tfw
<b>Support File for ADS</b>	SOCET SET support file	.sup
<b>RPC for Satellite</b>	RPC Model file	.rpc, .rpb, .xml, .txt
<b>Image Tiles for Satellite</b>	Tile Model file DIMAP	.til .xml
<b>SimActive Script</b>	SimActive Script Format	.spt, .txt
<b>Geoid</b>	GTX Format	.gtx
<b>Project File</b>	SimActive Format	.c3d
<b>3D Features</b>	ESRI Shapefile	.shp
<b>3D Model</b>	SimActive 3D Model Format OBJ Format	.tmf .obj
<b>Point Cloud</b>	LIDAR LAS LIDAR LAZ	.las .laz
<b>Contours</b>	ESRI Shapefile AutoCAD 2000 DXF	.shp .dxf
<b>Interior/Exterior Orientation File</b>	SimActive Format	.ieo
<b>Calibrated Reflectance Panels</b>	SimActive Format	.crp

Table 3: Supported file formats.

## 4.1 Sensor Types

---

Correlator3D™ supports the following types of sensors:

- UAV / Medium / Large format camera systems
- Multispectral camera systems with unregistered bands
- Satellite sensors using the RPC model
- Leica's ADS pushbroom sensors

These four sensor types function in a similar manner, but require different parameters when creating a project. The following flowchart describes the workflow of Correlator3D™. Note that the workflow is sensor-dependent.

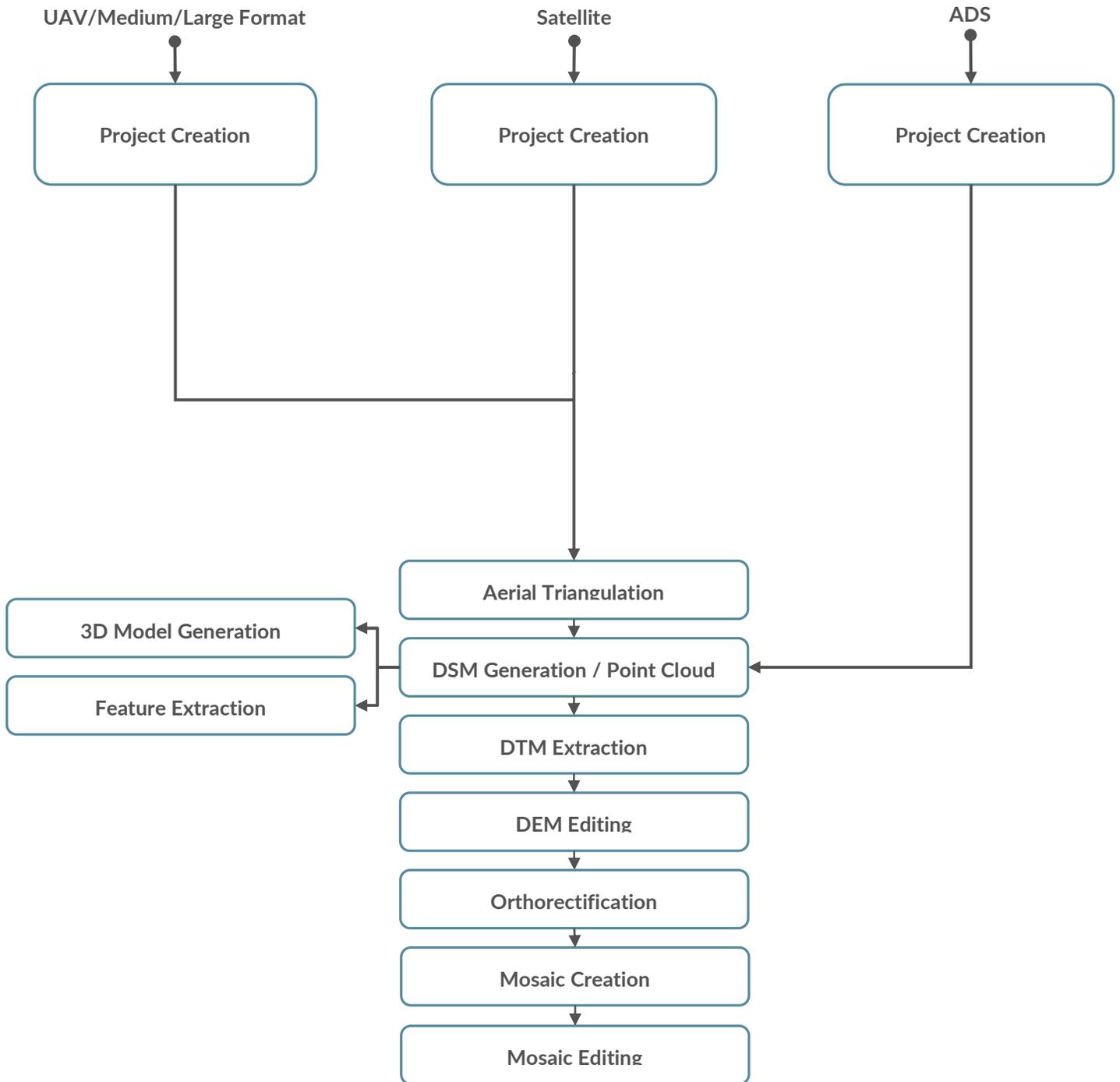


Figure 2: Correlator3D™ workflow.

## 4.2 Input Image Formats

---

### 4.2.1 Formats

Supported formats are summarized in Table 4.

Image Type	Data Format
TIFF, BigTIFF and GeoTIFF	8, 16 or 32 bits per band 1 to 32 bands Single page or multipage
JPEG in TIFF	8 or 12 bits per band 1, 3 or 4 bands Single page or multipage
LZW in TIFF	8, 16 or 32 bits per band 1 to 32 bands Single page or multipage
JPEG	8 bits per band 1 or 3 channels
JPEG2000	8 or 16 bits per band 1, 3 or 4 bands
IIQ	16 bits per band 3 bands
NITF	8 or 16 bits per band 1, 3 or 4 bands
Windows Bitmap	8 bits per band 1, 3 or 4 bands

Table 4: Supported input image formats



*TIFF and GeoTIFF images are supported in both interleaved (RGBRGB) and pixel ordered (RRGGBB) formats.*

### 4.2.2 Unregistered Bands

Correlator3D™ supports unregistered bands generated by multispectral or similar types of sensor. These sensors usually feature different imagers (and lenses) that are not registered or aligned mechanically. The software will register the different bands automatically during tie point extraction.

## 4.3 DEM Format

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The DEM should have square cells for all formats. This means that cell dimensions in X and Y should always be the same. Also, elevation values in GeoTIFF files should be expressed as 32-bit floating point numbers.

## 4.4 Orthophoto Format

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Orthophotos can be generated in the Tiled TIFF format with overviews to maximize system performance during their subsequent exploitation using GIS software. Orthophotos are produced in one of the following formats:

- 8, 16 or 32 bits per band
- 1 to 32 bands
- JPEG compression or no compression

## 4.5 Vectors

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Existing vectors can be supplied to the software for different purposes. They can be used as 3D constraints for the DSM generation and DTM extraction modules to force specific elevation values in the output DEM. They can also be used as an input to the orthorectification process to generate true orthos. Vectors can also be used as a reference in the software. For example, some projects can be divided in multiple blocks. Having an overlay displaying a reference can then be useful to guide the editing process.

Vector files must be provided in the ESRI Shapefile or Microstation DGN and contain points, lines or regions. If vectors are to be used as a 3D constraint but that the features do not have elevation data (z-component), users will be prompted to specify a default elevation value or to specify the name of the attribute to get the elevation from (e.g. "HEIGHT").



Figure 3: Vector elevation dialog.

## 4.6 Coordinate Systems

Correlator3D™ requires the projection to be specified when creating a project. The user specifies the projection details as shown in Figure 4.

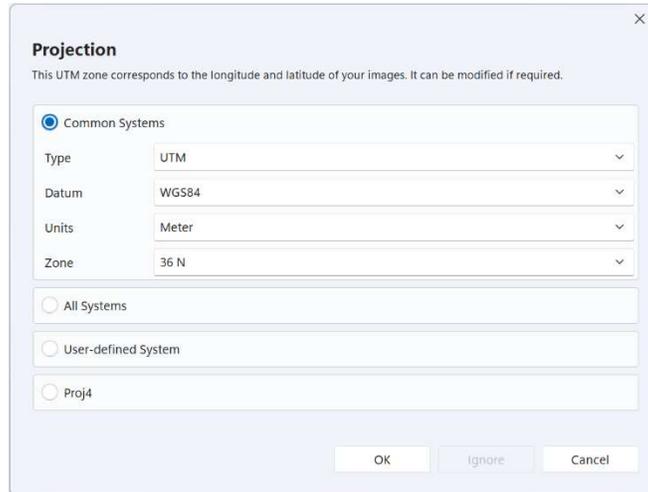


Figure 4: Projection dialog.

Four options are presented to the user. A predefined list of the most common projections is available. Otherwise, the user may search for a specific projection system by entering the corresponding keywords or EPSG code. The user can also specify a custom projection or specify a Proj.4 definition. If using the Proj.4 option, please refer to this website for specific values: <http://spatialreference.org/>

Although mandatory for satellite and ADS sensors, the projection is optional for UAV/medium/large format sensors, and can be ignored by pressing the “Ignore” button as shown in Figure 4. Note that the rotation system supported by Correlator3D™ is photogrammetric (omega, phi and kappa) and that the geographic coordinate system (i.e. latitude/longitude) and navigational angles (i.e. roll, pitch and yaw) are converted when importing EO data during project creation. If the user chooses to ignore the projection, then no projection information will be saved in the GeoTIFF files.



**Proj.4 values representing a geographic coordinate system (latitude/longitude) are not supported.**

# 5 VISUAL INTERFACE

Correlator3D™ is designed for ease of use, featuring a simple visual interface. The main window serves to load, save, and display DEMs, point clouds, mosaics, orthos, images, GCPs, vectors, contours and AT results. Additionally, it provides access to the different software functionalities and tools. At the core enabling this user experience is the project tree, further described in the corresponding section.

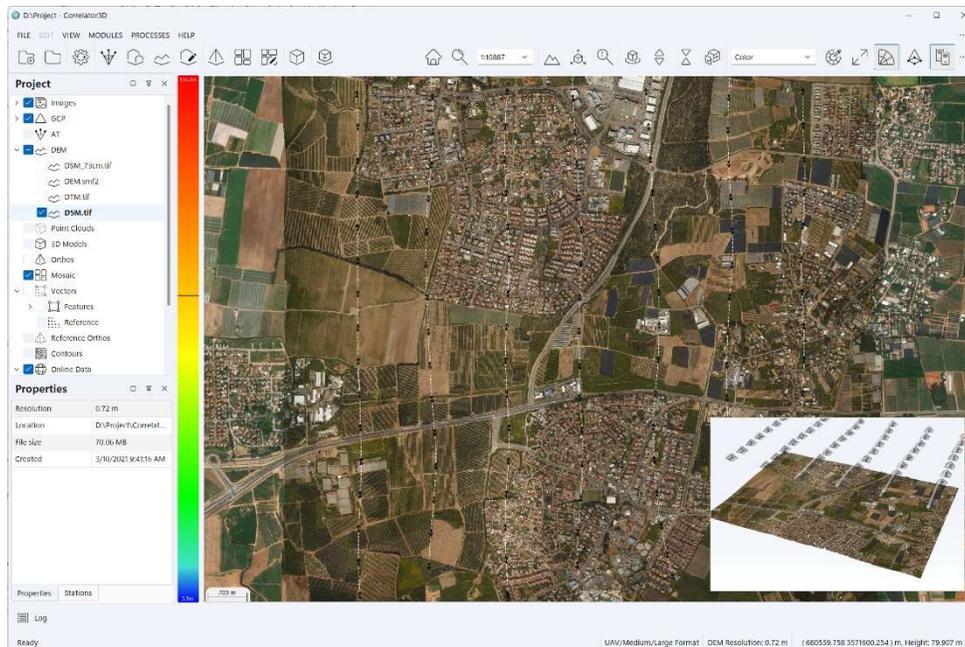


Figure 5: Correlator3D™ main window.

## 5.1 Multilingual User Interface

Correlator3D™ can be operated in different languages, including English, French, Portuguese, Spanish, Japanese, and Chinese. The user can select the language at any time by accessing the corresponding option in the General Settings dialog from the File menu. Note that the language change is only applied once the software is restarted.

## 5.2 Color Mode

The software features a color mode option that allows users to customize the appearance of the user interface to their preferences. Users can choose between a dark or light color scheme or set it to match the current Windows setting. The dark mode is particularly useful for working in low-light environments or reducing eye strain, while the light mode offers a brighter interface for working in well-lit environments. Setting the color mode to match the Windows setting ensures consistency

with other applications and can be especially helpful for users who switch between different software frequently. To change the color mode, users can easily access the general settings of the application and select their preferred option.

## 5.3 Project Tree

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The project tree displays the project information as a hierarchical structure on the user window. The tree is used to perform multiple functions: modify the visibility of an overlay using a checkbox, save results, add data to the project, etc. It allows the user to seamlessly transition between data within each project. When the cursor is placed above an item listed in the project tree, contextual buttons appear. The following subsections describe each aspect of the project tree.

### 5.3.1 Images

At the top of the project tree are the “Images”. This item is filled with parameters given during the project creation. When selecting the “Images”, the camera(s) used in the project appear with their corresponding image footprints if a DEM is loaded. It is possible to have more than one camera within each project, and consequently, within the project tree.

Expanding the camera node will allow the user to see its associated flight line(s). The user has the option to select which flight lines or images are to be processed in corresponding steps using the contextual buttons. With this, flight line and images can be disabled; they will not be considered while generating a DSM or orthos. Moreover, the checkboxes are used to toggle visibility in the main window of the corresponding item (image, flight lines, or complete image set).



*In the AT module, all images included in the project are considered; enable/disable have no impact and cannot be changed in this mode.*



When a DEM is loaded, the image footprints on the ground are displayed. This function can be turned on and off at the user's preference.

When images are selected using the tree, the image positions are displayed as arrows overlaid on the DEM. This is very useful when ensuring that both the imagery and 3D data span the same region. Note that each arrow indicates the top of the image. Flight lines and their direction are also displayed as dashed lines with arrows.



*When the cursor is placed over an arrow, a tooltip shows the name of the corresponding image. The user can also right-click on the image position to display the image in a separate window. The image will be rotated following its kappa-angle value. Panning is performed by clicking and dragging with the middle (wheel) mouse button while zooming can be performed using the mouse wheel. Note that several images can be displayed simultaneously.*



Within the aerial triangulation module, the arrows may be replaced by color disks to allow a quick assessment of the quality of the bundle adjustment process. Please refer to section 7.1.6 for details.

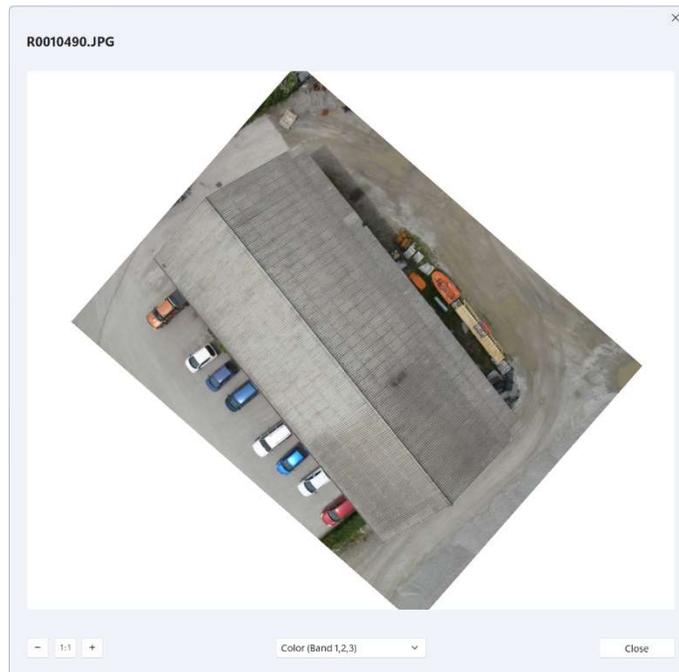


Figure 6: Image window.

### 5.3.2 GCP

An existing GCP file can be added to the project directly using the project tree. There is also the option to remove the GCP file from a project. In order to create a GCP file, the user can go into the AT module. Similar to the aforementioned option, the project tree can be used to toggle the GCP visibility using the checkboxes.

Correlator3D also allows the user to specify check points. GCPs and check points are stored in the same GCP file, but the project tree displays them in two distinct subcategories of GCPs. GCPs and check points are only considered when performing bundle adjustment, but can be used to visually assess quality of the DSM, DTM, and mosaic. Please refer to sections 7.1.3 and 11.5 for further details.

### 5.3.3 Calibrated Reflectance Panels

An existing calibrated reflectance panel file can be added to the project directly using the project tree. There is also the option to remove the file from a project. In order to create a panel file, the user must add one by one the reflectance panels with their respective images. Note that this section of the tree is only available with multispectral frame-based projects. Please refer to section 11.5 for further details.

### 5.3.4 AT

Please refer to section 7.1 for details.

### 5.3.5 DEM

The project tree simplifies working with DEMs as a DEM can be loaded directly onto it. Select “Add a DEM to project”, by placing the cursor over the “DEM” item in the project tree. More than one DEM can be a part of the project. However, at any given time, only one DEM can be displayed. The ability to toggle between multiple DEMs is possible through the project tree using the checkbox for each DEM. It is also possible to remove a DEM by clicking on the “X” when placing your mouse over the respective DEM.

Once the data is read, it will be displayed in the window. Two display styles are available for viewing elevation data: color and grayscale. If the color display style is selected, elevation values are mapped from blue to red (through green and yellow) according to the minimum and maximum values found in the data: low elevation values will be displayed in blue or green, middle values in yellow and high values in red. If the grayscale display style is selected, elevation values are linearly mapped from black to white according to the minimum and maximum values found in the data: low elevation values will be displayed in dark colors while high values will appear in light colors.

The display style can be changed by selecting “Display Style->Color” or “Display Style->Grayscale” in the “View” menu.

 Colors can be mapped from the minimum and maximum elevation values visible on the screen. The latter case is called “stretch” mode and can be enabled or disabled by selecting “Display Style->Stretch” in the “View” menu.

 Subtle variations in elevation values can be highlighted by selecting the “Shade DEM variations” feature, which simulates lighting and shadows. This feature can be enabled or disabled by selecting “Display Style->Shade” in the “View” menu.

When a DEM file is loaded, a legend is visible at the left of the main window. This legend shows the color mapping currently used for displaying the elevation data. Minimum and maximum values are displayed with a line indicating the “0” value, if relevant. When the cursor is moved over the DEM, a horizontal bar moves up and down over the legend providing a visual cue for the elevation under the cursor. Precise elevation and coordinates of the location under the cursor are available in the right part of the status bar. The legend can be shown or hidden by selecting “Legend” in the “View” menu.

 DEMs can be saved by clicking the contextual button in the tree.

### 5.3.6 Point Clouds

Point clouds are displayed under the “Point Cloud” section of the tree. The user can toggle their visibility by using the checkbox. Points clouds can be also be added by selecting “Add a point cloud to project”, by placing the cursor over the “DEM” item in the project tree. It is also possible to directly delete a point cloud from the project by hovering over the corresponding item and clicking on the “X”.

### 5.3.7 3D Models

3D models are displayed under the “3D Model” section of the tree. The user can toggle their visibility by using the checkbox. 3D models can be also be added by selecting “Add a 3D model to project”, by placing the cursor over the “3D Model” item in the project tree. It is also possible to directly

delete a 3D model from the project by hovering over the corresponding item and clicking on the “X”.

The user can also modify the way the 3D model is being displayed. If the model has a texture, its visibility can be toggled. It can also be displayed as a wireframe. These options can be accessed in the “3D Model Display Style” section of the “View” menu.

### 5.3.8 Orthos

With the project tree, the user can toggle the visibility of each generated ortho with its checkbox. It is possible to directly delete all the orthos from the project by hovering over the “Orthos” item on the project tree and clicking on the “X”. The user can also specify a new or existing folder for orthos. In order to do this, place the mouse over the “Orthos” and select the “+” icon to open or set a new ortho folder. Note that generating orthos without specifying a new folder will delete the previously stored orthos from the folder.

The user has the option to select which orthos are to be processed in mosaic creation using the contextual buttons. With this option, orthos can be disabled; they will not be considered while generating a mosaic.

### 5.3.9 Mosaic

The user can toggle the visibility of the mosaic using the project tree by using the checkbox. It is possible to directly delete the mosaic from the project by hovering over the “Mosaic” on the project tree and clicking on the “X”. The user can also specify a new or existing folder for the mosaic. In order to do this, place the mouse over the “Mosaic” item and select the “+” icon to open or set a new mosaic folder. Note that generating the mosaic without specifying a new folder will delete the previously stored mosaic from the folder.

### 5.3.10 Vectors

Vectors in a project are divided into two categories: Features, and References. Features are associated to 3D constraints and user selections and can be edited in the DEM Editing, Volume Calculation and Feature Extraction modules. The user can toggle the visibility of the different vectors using the corresponding checkbox. References are used to guide the user and serve to ease any aspect of the production, mostly editing. They can contain any type of vector, including project division, waterbodies, etc.

### 5.3.11 Reference Orthos

Reference orthos are orthos that were created outside of a project and are used for quality assessment. The AT module can also use the reference orthos along with a DEM as horizontal and vertical reference data when GCPs are not available.

The functionality of the tree view with respect to the reference orthos is the same as the one described in section 0. Note that disabled reference orthos will not be considered while performing a bundle adjustment with reference imagery.

### 5.3.12 Contours

The user can toggle the visibility of the generated contour lines using the project tree and its checkbox. Existing contours can be added by placing the cursor over the “Contour” item in the project tree and selecting “Open contour”. Note that more than one contour can be part of the project. It is also possible to remove a contour by clicking on the “X” when placing your mouse over the respective contour item. Contours can be saved by clicking the contextual button in the tree.

When a contour is selected using the tree, it is displayed as lines in the main window. Hovering the cursor over a specific line will pop up the corresponding elevation. It is also possible to click on a specific line to highlight it.

### 5.3.13 Online Data

If a projection was specified during the project creation, the user can toggle the visibility of online data. These data are automatically downloaded from the internet and can help assess the geolocation of the project. Online data can be either satellite imagery, maps, terrain data, or hybrid. These options can be selected directly from the tree or from the “Online Data Style Option” in the “View” menu.

## 5.4 Properties

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The project tree includes a window that displays the properties of a selected object (e.g. GCP, camera, images, DEM, orthophotos). The tool is beneficial as it assists in the assessment of metadata, such as the camera calibration, image position, GCP type, etc. The information the property window displays is dependent on the type of object selected.

## 5.5 Zooming and panning

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The main window of Correlator3D™ supports advanced zooming and panning capabilities. Data caching and automatically triggered refreshes are performed to offer both rapid and fluid response, while displaying the most accurate information available. Fast results are obtained even for huge projects at low memory costs. When working with large files, hard disk performance can limit the speed at which information can be displayed. In such situations, Correlator3D™ will temporarily display a less accurate version of the data while it is being loaded. The accurate version will be displayed shortly afterward, as soon as available.



*This allows the user to continue panning and zooming while data loading is performed and ensures a fast response at any given moment.*

Panning is performed by clicking and dragging with the left or middle (wheel) mouse buttons.



**Note that during DEM editing, only the middle (wheel) button is supported for panning.**

Zooming can be performed in multiple ways. The simplest and most intuitive way is to use the mouse wheel. If the mouse does not include a wheel, the options “Zoom->Zoom In” and “Zoom->Zoom Out” in the “View” menu will provide the same results.

 The “Zoom to region” feature lets the user specify a rectangular area. Zoom and pan operations are then computed to show the selected area as large as possible and centered onscreen. The “Zoom to region” feature is available by selecting “Zoom->Zoom to region” in the “View” menu.

 At any time, the user can return to the default view by selecting “Zoom->Home” in the “View” menu. The default view displays the entire project centered onscreen.

## 5.6 Image Band Setup

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 The Image Band Setup dialog allows the user to select which band of the image to use for each color channel (red, green and blue). This allows to analyze multi-spectral imagery in many ways. To view just a single band, the same band can be selected for all three channels. Default black and white bands are also available to provide other combinations. Note that the configuration can be set independently for each layer of the project (input imagery, orthos, mosaic, etc.).



Figure 7: Image band setup window.

 *For projects with unregistered bands, displaying images before band registration (which is performed automatically during tie point extraction) can lead to blurry images.*

## 5.7 Picture-in-Picture 3D Viewing

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Correlator3D™ features picture-in-picture (PiP) 3D viewing capability. The PiP brings a 3D rendered view of projects through an inset window, visible at all times to streamline processing and editing. The interactive viewing capability allows display of image locations and associated viewing pyramids, as well as DSMs, DTMs, point clouds, orthophotos and mosaics. Ground control points, check points, and aerial triangulation results are displayed in 3D to facilitate quality control. The PiP allows a 3D visual assessment of data and results throughout the entire production workflow, including real-time modifications displayed during DEM editing.

The PiP window always reflects in 3D what is currently displayed in 2D in the main view. For example, zooming in the main window will result in cropping the data shown in the 3D view.

Therefore, users willing to inspect a feature in more detail should first zoom in the main window, and then interact with the PiP window.



At any time, the 2D and 3D views can be swapped by pressing the corresponding button in the toolbar.

The size of the PiP window can be set to small, medium, or large in the in “View->3D View” menu. Users can also have the 3D view in its one window by selecting “3D View->Window” in the “View” menu.

Rotation in the PiP window is performed by clicking and dragging with the left mouse button. Zooming can be performed by using the mouse wheel, while panning is done by clicking and dragging with the middle (wheel) mouse button. The left button of the mouse can be used to select an object like an image pyramid to see its footprint.



Users can always reset the view point to its original state using the corresponding button in the toolbar.



Elevation values of objects being displayed in the 3D view can be exaggerated or suppressed to facilitate data analysis. To achieve this, users can repeatedly press the corresponding buttons in the toolbar.

## 5.8 Scale

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The user can also zoom the current view to a specified scale. For example, to make 1 centimeter on the screen to be equivalent to 1 kilometer of ground truth, one would enter a scale of 100,000 (this is the number of centimeters in a kilometer).

A scale indicator is located near the bottom of the legend. The indicator can be shown or hidden by selecting “Scale” in the “View” menu. The scale is dynamically adjusted during a zoom operation.

## 5.9 Status Bar

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The status bar provides various types of information, including the sensor type, the DEM horizontal resolution, the coordinates of the cursor and the elevation at the cursor’s location. The sensor type is either “UAV/Medium/Large Format”, “Satellite” or “ADS” and indicates the current project type. The DEM resolution displays the resolution of the DEM written in the file. Unlike the scale, it is invariant to zooming operations. Coordinates are refreshed while the cursor is moved over the DEM and the elevation under the cursor is displayed only when available. The status bar can be shown or hidden by selecting “Status Bar” in the “View” menu.

## 5.10 Profile



The Profile tool generates a vertical profile of the DEM over a user-specified path. The path consists of a series of connected linear segments. Once a path is specified, Correlator3D™ opens a new window containing the vertical profile. The profile is generated by sampling the DEM and contains two different representations simultaneously.

The first representation is an area chart shown in light blue. It shows the real elevation value for each sample based on a nearest neighbor approach for samples falling between two values of the DEM. It provides a discrete representation that is well-suited for visualizing surfaces that are highly non-continuous (e.g. urban areas).

The second representation is a smooth dark blue line super-imposed over the previous representation. This time, a bilinear interpolation technique is used to obtain the sample values. The representation is better suited for visualizing areas where the terrain is continuous (e.g. rural areas).

In the profile windows, vertical blue lines show the delimitation of each linear segment of the path.

When the mouse is moved over the profile, a blue circle located on the interpolated profile follows the mouse motion. XY coordinates and elevation values associated with this blue circle are automatically updated and shown in the lower right corner of the profile window. A similar circle appears and moves synchronously in Correlator3D™'s main window over the user-specified path to show the exact location corresponding to the mouse position in the profile view.

A “stretch” button located in the status bar enables or disables the stretch mode. When enabled (default), the profile is stretched to take the entire size of the window, but the aspect ratio is not respected. When disabled, square aspect ratio is used, ensuring that the same number of pixels in the x or y dimensions correspond to the same physical dimension in DEM units.

By right-clicking on the profile, the user can save an image of the profile in a file or to the clipboard.

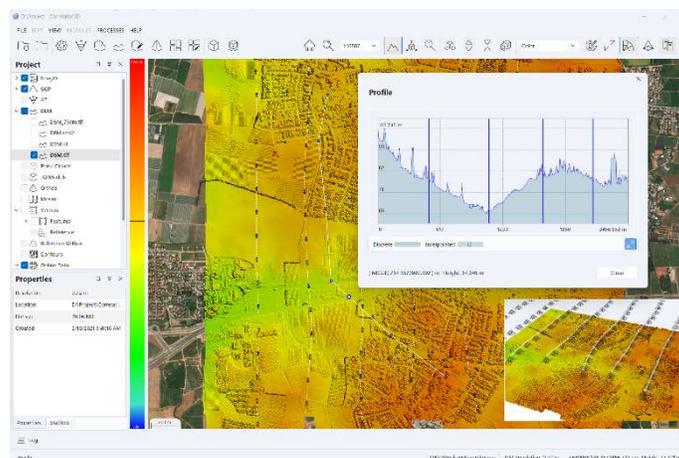


Figure 8: Profile window.

## 5.11 Volume



The Volume tool measures a volume over a user-specified selection and a reference elevation. The user begins by selecting the areas in which the volume is to be calculated. The functionality related to the selection is similar to the DEM Editing module. Please refer to section 7.4 for details.

Once areas are specified, the user clicks on the corresponding button to open the Volume window and selects a reference elevation for the volume to be computed. There are five types of reference elevations:

- Interpolate DEM at polygon boundary: obtain volume by interpolating DEM values present at the chosen boundary
- Interpolate polygon elevation: obtain volume by interpolating elevation values defined in each polygon vertex
- Use fixed elevation: obtain volume from a specified height
- Remove constant offset (dig): obtain volume by removing an offset value
- Add constant offset (fill): obtain volume by adding an offset value
- Use reference DEM: obtain volume by selecting a reference DEM

These options give the user flexibility in the volume type they can calculate.

The following statistics appear in the properties windows on the left once the process is complete:

- Volume (Cut): the volume measured between the reference elevation, and the terrain above
- Volume (Fill): the volume measured between the reference elevation, and the terrain below
- Terrain area: the area covered by the selection, considering the terrain morphology. This can be visualized as the size of the sheet you would require to drape the terrain
- Orthogonal area: the area covered by the selection, not considering the terrain elevation
- Volume coverage: percentage representing the coverage of the selection used to measure the volume, with no consideration for the undefined elevation values. The user should ensure that this value is always close to 100%. The value may indicate that the reference DEM being used does not overlap completely with the current DEM, or that the software was not able to completely interpolate at selected boundary (because too many vertices were falling outside the model).

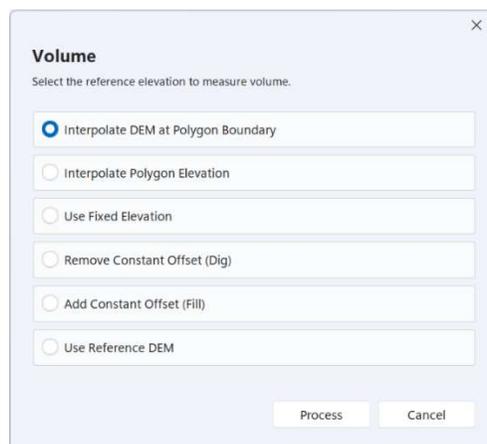


Figure 9: Volume window.

## 5.12 Data Source Identification

 The Data Source Identification tool can be used to identify which image, ortho, or DEM tile was used to generate a specific product at a specific location. This is particularly useful to better understand why an undesirable feature appears in a DSM or a mosaic for example and identify its origin. More specifically, when users click on a location using this tool in the main view, the Data Source Identification window will present the following information:

- **DEM Tiles:** the list of temporary DEM tiles, with their respective elevation, used to generate the final DSM at this location. These tiles can be found in the temporary folder as described in Section 15.3. A strategy to merge back the tiles, excluding the ones that are undesirable, is also explained.
- **Mosaic:** the list of orthos, with their respective color value, used to generate the mosaic at this location. Having more than one ortho means that the location is within a feathering (transition) zone between two or more orthos.
- **Orthos:** the list of orthos for which the footprint contains the selected location.
- **Images:** the list of images for which the footprint contains the selected location. Note that a DEM must be loaded.

Note that clicking on an ortho/image from these lists will automatically select the corresponding item in the project tree. Consequently, it can be disabled using the contextual button, excluding it from any further process.

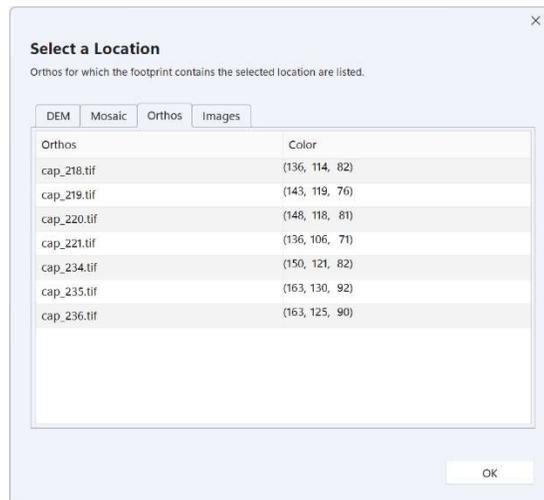


Figure 10: Data source identification window.

# 6

## PROJECT CREATION

The simplistic design and interactive user interface is made possible through the creation, and use, of projects. A project within Correlator3D™ consists of a file with information about the location of all the input and output data: EO data, camera calibration, AT data, projection, images, DEMs, GCP, orthos, mosaic, reference orthos and vectors. The purpose of the project is to centralize information for ease of use. Part of this information must be specified during project creation.

The project creation wizard is used to create a project in Correlator3D™. As the wizard incorporates all supported sensor types, the user does not have to be concerned with the specific sensor type for the full photogrammetry workflow. A project type must be simply selected from one of five options, and proceed with the required steps.

Once a project has been created, it can be closed and accessed at a later time. A project can be moved from one location to another, as long as the file hierarchy is preserved on disk (e.g. one folder with the project file and all images, orthos).

To save the main file of a project, the user can select “Save Project As” within the File menu. This will not change or move the other files, only the main one.

There are four types of projects differentiated by the sensor type and image size: UAV, Medium/Large Format, Satellite and ADS. The following sections describe the steps to create a project for each of the listed project types. As the UAV and Medium/Large Format project types only differ in image size, they are grouped together.



Figure 11: Project type.

## 6.1 UAV / Medium / Large Format

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The UAV/medium/large format imagery refers to digital images and scanned films. The difference with each is based on the image size. The UAV format is used for digital images smaller than or equal to 50MP. The medium/large format is used for images greater than 50MP, and for scanned films.

UAV/medium/large sensor the user should ensure that the overlap between adjacent images is appropriate to ensure optimal results. The endlap (i.e. the overlap between successive images) should be at least 60% of the image size, but also should be as close as possible to that value. In terms of the sidelap requirements (i.e. the overlap between images from adjacent flight lines), it is recommended to use a value between 20% and 30%. Note that for low-altitude flights, the endlap should be approximately 80% and the sidelap 50% to minimize occlusion effects from one image to the other.

### 6.1.1 Step 1 – Camera Configuration

While most setups only consist of a single camera, more than one camera can be added to a project. If there is more than one camera, those cameras can either belong to the same group (e.g. a multi-head camera systems), or to different groups (e.g. an area was flown by two different cameras that are not attached together). This can be performed by specifying the number of cameras, and the number of groups, and then associating each camera to its group using the table. Note that the name of each camera can also be changed in this table.

A camera can also consist of more than one imager. This is the case for multispectral cameras where each frame consists of several bands that are not aligned together. The user must then check the “Unregistered Bands” option. Note that even if a camera consists of several imagers, it is still considered as a single camera.



*The band registration process will be performed automatically during the tie point extraction.*

Depending on the number of cameras, the wizard will cycle through the “Image Selection” and “Camera Parameters” steps iteratively.

### 6.1.2 Step 2 – Image Selection

The selection of images to be processed in the project is done by adding the images and their corresponding EO data in the wizard. Images can be added individually, or through a complete folder using the appropriate button. Once they are added, the software automatically requests EO data (please refer to section 11.1 for further details). If EXIF information is present, the software can use it to generate the EO data, though it is not mandatory. The user has the option to import a text file, or a legacy SimActive EO file. Projection information is defined after this dialog (please refer to section 4.6 for further details).

The user can remove all selected images using the “Clear” button, choosing a new set of images instead. Specific images can be removed from the dataset using the “-” button on the right of the list of selected images.

The workflow is different when the “Unregistered Bands” option was checked in the “Camera Configuration” step. If the sensor is natively supported, the user can simply select all images from all bands and the software will automatically organize them in a table where each line corresponds to a frame, and the columns to its different bands. Otherwise, the user can select images band per band and the software will ask how to integrate them to the list (e.g. append them to an existing band or create a new band). Note that it is very important to make sure that all lines contain the right images/bands to ensure frame consistency. Once all images are added, the name and index of all bands can be modified by pressing the “Edit bands...” button. A master band can also be selected. This band will be considered as the reference when registering the other bands as well as having a greater weight when generating the DSM. The user can then import the EO data by pressing the “Next...” button.

### 6.1.3 Step 3 – Camera Parameters

Camera parameters for all cameras of the project must be specified. The user can import a legacy SimActive camera file. Alternatively, the software can detect the values automatically, including the focal length and pixel size. “Digital – Polynomial” is the suggested type for non-metric cameras similar to those normally used on UAVs. More information on different camera calibration types can be found in section 16.1. If the user is working with scanned films, the fiducial detection tool will be shown (please refer to section 11.4 for further details).



**Although parameters can vary from one camera to the other, only one calibration type is supported for a given project. For scanned films, if the dimensions of images in pixels vary, then the smallest width and height values observed should be specified. Note that these minimum width and height values may come from two different images.**

### 6.1.4 Step 4 – Project Parameters

In this step, the user defines the project location by clicking on the “...” button. There is the option to specify a projection, however, it cannot be different than the one selected for the images in Step 1.

The other project parameters are optional. The “DEM” option allows the user to specify (e.g. SRTM) a reference DEM.

With the “GCP File” option, the user can specify a file containing GCP and check point information. The file can be an existing one or it can be created by importing data from a text file (please refer to section 11.5 for further details).

The “Reference Orthos” option lets the user browse and select a folder containing the reference orthos.



*Both GCPs and reference orthos can be specified during project creation. However, when performing bundle adjustment, the user will need to select a single ground reference.*

## 6.2 Satellite

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### 6.2.1 Step 1 - Image Selection

The metadata of a satellite image is stored in its corresponding RPC file. This file comes in several formats, all of which are supported by Correlator3D™. When creating a project, the user must specify the input RPC files of the images to be processed. Correlator3D™ automatically parses these files to recover the satellite parameters. For large satellite images, the images may be tiled and referenced by a TIL file. This TIL file will be required as an input. Only one (1) RPC file is needed per TIL file. The project creation wizard will automatically suggest an image file when an RPC file is selected first.

The user has the ability to remove all selected images using the “Clear” button, choosing a new set of images instead. Specific images can be removed from the dataset using the “X” button on the right of the list of selected images.

### 6.2.2 Step 2 - Image Pairing

In order to generate a DSM using overlapping satellite images, the user must specify image pairs. Each pair will be used to generate a corresponding DSM, with the results merged at the end of the process.

To construct a pair, select each of the images to be paired using the drop-down menu, and click on “Add”. A star (\*) before the name of the image in the drop-down menu indicates that the image has not been used in any pair thus far.

This step can be skipped if no DSM is required or if there is only one satellite image in the project.

### 6.2.3 Step 3 – Project Parameters

In this step, the user defines the project location by clicking on the “...” button. It is mandatory to specify a projection. The projection can be specified by selecting an existing DEM with a valid projection in it.

The other project parameters are optional. The “DEM” option allows the user to specify (e.g. SRTM) a reference DEM.

With the “GCP File” option, the user can specify a file containing GCP and check point information. The file can be an existing one or it can be created by importing data from a text file (please refer to section 11.5 for further details).

The “Reference Orthos” option lets the user browse and select a folder containing the reference orthos.



*Both GCPs and reference orthos can be specified during project creation. When performing bundle adjustment, the user will need to choose which ground reference to use as they cannot be used simultaneously.*

## 6.3 ADS

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### 6.3.1 Step 1 - Image Selection

The metadata of an ADS image is stored in a standard SOCET SET support file. This support file is an ASCII file that uses keywords. When creating a project, the user must specify the support files of the images to be processed. Correlator3D™ automatically parses these files to recover the names of the images, the camera calibration files, and the exterior orientation data. Therefore, the user must make sure that all file names and paths specified in the support file are valid.



In the ADS support files, paths containing spaces are not valid.



Correlator3D™ only processes level 1 (L1) imagery for ADS sensors.

### 6.3.2 Image Pairing

In order to generate a DSM using ADS imagery, the user must specify image pairs. Each pair will be used to generate a corresponding DSM, with the results merged at the end of the process.

To construct a pair, select each of the images to be paired using the drop-down menu, and click on “Add”. A star (\*) before the name of the image in the drop-down menu indicates that the image has not been used in any pair thus far. This step can be skipped if no DSM is required.



*Better results in ADS mode will be achieved if the angle between the sensors is small (i.e. forward-nadir or nadir-backward). Using the pair forward-backward is likely to generate noisy or erroneous results due to occlusions (objects visible in one image might not be visible in the other).*

### 6.3.3 Project Parameters

In this step, the user defines the project location by clicking on the “...” button. It is mandatory to specify a projection for an ADS project. The projection can be specified by selecting a DEM with a valid projection; it must correspond to the one specified in the support files.

# 7

## DATA GENERATION

### 7.1 Aerial Triangulation

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Correlator3D™ includes an aerial triangulation (AT) module for UAV/medium/large format sensors and satellite sensors, which automatically improves exterior orientation values and camera calibration parameters from the image data. It is therefore recommended to perform this process on every project to ensure the quality of the geospatial products generated from the imagery. The software requires as a minimum overlapping aerial images, coarse GPS measurements, and basic camera parameters.

It is worthwhile to spend time on the AT step, as it will help save significant processing time on subsequent steps.

To enter this mode, the user must select “Aerial Triangulation” in the “Module” menu. Aerial triangulation should be performed in the following order:

1. Flight Line Editing (if required)
2. Tie Point Extraction
3. GCP Creation (if required)
4. Tie Point Editing (if required)
5. Bundle Adjustment
6. Quality Assessment
7. Image List Filtering (if required)

#### 7.1.1 Flight Line Editing



Projects sometimes include images that should not be considered during processing in order to obtain better results. For example, images taken during takeoff or landing, or when changing flight direction should be removed at the beginning of the project. This can be done using the Flight Line Editing mode.



In this mode, the user can first select individual images in the main view (or multiple images using the rectangular selection tool) and delete/undelete them from the project. Note that deleting images will not delete the images from the disk, but only remove them from the project. The same operations can also be performed from the project tree. For example, a complete flight line can be selected and deleted using the corresponding contextual button.



The configuration of the flight lines can also be modified. The user can use the Connect/Cut tool to merge two flight lines together or cut one into two halves. This is particularly useful in the context where DSM tiles are generated on a per-image-pair basis and that a tile cannot be generated using two images from two different flight lines. To use this tool, the user simply needs to select a first image, and drag the cursor to the next image. If the images are already part of the same flight line, this one will be cut. If not, the two flight lines will be merged. Again, the same operations can be performed from the project tree by selecting two flight lines and using the corresponding contextual button.



Another strategy is to use the Automatic Flight Line Calculation tool. In this case, Correlator3D™ will compute the flight lines from scratch, based on flight direction and endlap. Note that any previous flight line modification will be overwritten.

When exiting the Flight Line Editing mode, the software will add a new step to the AT List of the project tree. If other modifications are applied afterward to the flight lines, the list will grow displaying all iterations. This allows flexibility to back track in case of an undesirable iteration. Specifically, the last iteration may be undone or the user may choose to come back to results of a specific iteration. Note that if a bundle adjustment was performed, a new quality report will be automatically generated to reflect the new changes.

### 7.1.2 Tie Point Extraction



The next step is to extract tie points, which is performed automatically. A tie point is an image feature that is visible in two or more images. Correlator3D™ offers two types of tie point extraction: standard and exhaustive. The standard extraction type is suitable for most projects, while the exhaustive type is better fitted for challenging datasets with suboptimal inputs.



*Exhaustive tie point extraction is usually slower than standard tie point extraction. It is suggested to use the exhaustive type only when the standard one does not generate optimal results (e.g. several images that are not connected to others).*

If reference orthos are present, the tie point extraction process will also extract points in those images, even if their ground sampling distance is different. Note that these observations will be used during bundle adjustment only if the Ground Reference option is set to “Reference Orthos”.



*When processing projects with unregistered bands, the band registration process will be performed automatically during tie point extraction.*



**Compared to bundle adjustment, the tie point extraction process is the most time consuming. If the user needs to perform numerous bundle adjustments on the same project, then tie points do not need to be recalculated each time.**

### 7.1.3 GCP Creation

Next, the user must decide whether to use ground control points (GCP). Although not required for relative accuracy, ground control points are necessary for absolute accuracy. The quality of the ground control points will have a strong impact on the results. Ground control points have two benefits. First, they ensure that there is no global spatial offset (i.e. xyz translation) in the refined values. Second, they provide another means to validate the residual error of the refined values.

The user can also create check points. These are special GCPs that will not be considered during bundle adjustment, but for which statistics and reports will be generated. Check points are used to assess the quality of the bundle adjustment using an independent data set.

The GCP Editing tool helps the user locate GCPs in the images by selecting the best image candidates, and estimating where the GCPs should fall in those images. Correlator3D™ relies on the exterior orientation parameters and camera calibration data located in the IEO file. Upon entering the GCP Editing tool, the software will verify the average residual error and suggest the user to perform an estimation of IEO parameters if this error is too large. This will add an “Estimate” AT step to the project tree. When GCP creation is completed and bundle adjustment is performed, the “Estimate” step will be automatically removed. Therefore, the “Estimate” step has no impact on the bundle adjustment process. The GCP Editing tool is described in Section 11.6.

### 7.1.4 Tie Point Editing

After the initial automatic tie point extraction step has been performed, the software will display links created between images. Hovering the mouse over any link displays the number of tie points present between those images.

The user can right-click on any link to visually inspect or edit the tie points between two images, ensuring features match in both images. They can also right-click on the image position to display the image itself, with all its feature points displayed as an overlay.

 Under some circumstances, it may not be possible to automatically extract tie points between some images. This is more likely to occur when the overlap is too low or the quality of images is not sufficient. The user can then manually add tie points to the project. A link can be added between two images by clicking on the corresponding button, by clicking and holding the left button on the first image and by dragging the link to the second image. The tie point editing dialog will appear with the two corresponding images. The user can zoom in using the mouse wheel, and pan by clicking and dragging with the center button (wheel).



Figure 12: Tie points between two images.

At this point, the objective is to add as many tie points as possible. To do so, the user must left-click on one feature in one image, and drag it to the corresponding feature in the second image. The software will then automatically try to refine the match, and will display the Tie Point Editing window. In the window, the user can either validate or refine the position of the feature in each image.

A tie point is more beneficial when the feature is identified in multiple images. Due to this, user should always consider using such features, distinguished as colored stars in the images. If the user clicks on one of these stars, then drags to the corresponding feature in the other image, the software will display the Tie Point Editing window. Multiple images containing the feature will be displayed in the ribbon. The new observation for the tie point will be identified with its name in blue.

 When the ribbon is dragged completely to the left (therefore showing the rightmost part of the ribbon) a special “+” button is visible. Clicking this button will also add new image candidates to the ribbon.

As the user enters more tie points, the software will adjust the relative orientation of the two images to facilitate the task. Also, when moving the cursor in one of the two images, the software will provide a predictor (shown as a multicolored circle) in the other image to give a hint of where the feature should approximately appear. This helps facilitate the process.

 At all times, the user can select a tie point to edit by either right-clicking on it, or using the corresponding button.

 The user can also select a tie point to delete it using the corresponding button.

There is no specific rule on how many tie points should be added between two images, although 5 or 6 is a good approximate.

Note also that the goal is not necessarily insuring that there is a link between every corresponding image. For example, adding a link between a pair of images can tie two flight lines together, but it is not necessary to link each adjacent images in the flight lines. Instead, the links can be added on image pairs that are well dispersed (e.g. one image pair in the beginning, middle, and end of the flight lines). This can save the user time, while ensuring that the overall project is connected.

### 7.1.5 Bundle Adjustment

Bundle adjustment derives adjusted exterior orientation and camera data. Correlator3D™ can be used to perform a boresight calibration or a full AT adjustment. In the boresight calibration process, the software computes the error component that is common to all exterior orientation estimates. This corresponds to the relative position/orientation of the camera to the GPS/IMU unit. If a full AT adjustment is selected, then the software still automatically performs a boresight calibration beforehand but also computes a unique correction for each individual image.

The software can also be used to perform a camera calibration in parallel to the EO adjustment. The software adjusts camera parameters based on the camera type used. These values may include focal length, principal point, LUT values, as well as radial and decentering distortion parameters. Various camera models are supported and described in Appendix A.

When available, the user can use either ground control points or reference orthos to ensure that there is no global spatial offset (i.e. XYZ translation) in the refined values.

When using ground control points, Correlator3D™ takes into account user error when identifying the GCP location in the images and also accounts for possible error in the XYZ coordinates. In the bundle adjustment settings, the user may specify uncertainty values for the GCP. The "Pixel Radius" is the presumed error when defining the GCP locations in the image using the GCP Editing tool. For example, a value of 0.5 means that the user predicts having introduced an error of half a pixel when defining the GCP location in the image.

The bundle adjustment settings let the user specify a general uncertainty for the "XY" and "Z" components of the GCPs. For example, an uncertainty value of 1m for the "XY" field will allow a 1m fluctuation to the XY values of the GCPs, whereas a value of 0m implies the user has absolute confidence in the GCPs. This will force the software to comply with the GCPs exactly when performing an EO adjustment. This setting only applies to GCPs that do not have per-point uncertainty values.



*Per-point uncertainty values are specified using the GCP Editing tool. Different XYZ uncertainties can be specified for each GCP. When available, these values override the aforementioned general uncertainty values.*

When GCPs are used, final residual analysis and statistics will also be computed for the check points.

If reference orthos are used, tie points detected in these images will provide horizontal (XY) anchoring to the project. If a DEM is currently loaded in the user interface, it will provide vertical (Z) anchoring. While optional, the use of a reference DEM is recommended.



Bundle adjustment can be run in two (2) modes. These are called "Constrained" and "Unconstrained" and apply to the camera calibration and EO adjustment settings. The EO adjustment setting also allows for a boresight adjustment only or for RTK/PPK assisted systems. The unconstrained mode performs all necessary parameter allocations for the user. It is designed to provide the fastest AT solution. The constrained mode requires specification of the bundle block settings, providing more control over the project.

In the constrained mode, the user can lock one or more parameters for bundle adjustment. These locked parameters can come either from the EO values and/or the camera values. For example, if the GPS and camera data are known to be accurate, the user may choose to lock them and only process the IMU portion for bundle adjustment. This would force the software to perform bundle adjustment only on the IMU portion of the EO values.

In the constrained mode, the user is also required to define a search space for the easting (x), northing (y), elevation (z), omega, phi and kappa values. The search space defines the assumed uncertainty regarding the accuracy of the input data. For example, specifying an uncertainty of 5m for easting and an uncertainty of 2° for omega, restricts the software to adjust the easting and omega parameters from their current positions as defined by the input to a maximum of 5m and 2° off respectively, in the output.

Note, in a full AT adjustment, the uncertainty value bounds only the full AT portion of the adjustment, meaning only the unique correction for each image will be bound by the uncertainty value. The boresight portion of the adjustment, which is automatically performed during any full AT adjustment, will not be bound at all. For example, if a 5m value in X was chosen as the uncertainty for a full AT adjustment, then as a first step, a common boresight correction of any appropriate magnitude (as determined by the software) will be applied to all images followed by a unique correction to each individual image of up to 5m in X. The user may change this behavior by unchecking the "Perform Boresight Calibration" option. With this option unchecked, the software

will skip the boresight calibration process, making sure the uncertainty range is respected during the adjustment.

The "RTK/PPK Assisted" option should only be used when the GPS data are known to be accurate. In that case, the software will only adjust the orientation parameters.



**The search space must be appropriately large to compensate for the EO errors. Large average residuals may imply that the search space was too small and that results are not optimal.**

In the case of satellite sensors, the AT process will calculate corrections on RPC values to improve the accuracy of the georeference. The software requires overlapping satellite images and RPC data. GCPs may also be used to ensure absolute accuracy. The EO refinement process will automatically adjust the RPC values and output the RMS pixel error. Note that if the project contains only one image, GCPs will be required to perform AT.

For satellite projects, another type of EO adjustment called "Image Offset Correction" is available. Using this mode, the software will minimize for a 2D translation in each image frame. This type of adjustment is particularly useful when GCPs are not available or when the solution must be constrained even more.

Finally, an option to remove images having a tie point residual error higher than the specified threshold is provided. This option is equivalent to the Image Filtering functionality described in section 7.1.7 except that it is performed through the bundle adjustment process. Selecting "Automatic" will make the software to calculate the average residual error for all images, and use a threshold corresponding to five times this value.

### 7.1.6 Quality Assessment

Once the bundle adjustment has been performed, the user is presented with the overall tie point residual error expressed as colored circles centered on each image. There are four different colors:

- Green: when the residual error is less than 0.75 pixel
- Yellow: when the residual error is between 0.75 and 1.5 pixel
- Red: when the residual error is larger than 1.5 pixel
- Blue: when it was not possible to correct the position/orientation of the image (e.g. no tie point)

Note that it is normal for the residual errors to be red in the initial step. It simply means that bundle adjustment is necessary to bring the values down to the green range. Tie points, ground control points and check points, when available, are also displayed using the same color coding. By hovering the mouse over a point or an image, the user can see the associated residual error in the right hand side of the status bar.

At any time during AT, the user can switch between the color-coded circles and the kappa arrows by selecting the corresponding option in the "View" menu. The "IEO Display Style" option applies to images while the "GCP Display Style" option applies to GCPs. For GCPs, a third display style is also available: Spatial Residuals.

The spatial residual is the difference between the specified coordinates of the GCP and the theoretical coordinates that are triangulated using the current IEO data. When the “Spatial Residuals” display style is selected, each GCP and check point is represented as a set of two arrows. The red arrow shows the vertical residual error. A red arrow pointing up indicates that the specified GCP altitude is higher than what is triangulated from the IEO data. The blue arrow shows the planar residual error. A blue arrow pointing north-east indicates that the specified GCP coordinates are north-east of what is triangulated from the IEO data.

In the software interface, an AT List is displayed on the left hand side detailing the AT steps that have been performed. As more bundle adjustments are performed, the list grows displaying all iterations. This allows flexibility to back track in case of an undesirable iteration. Specifically, the last bundle adjustment operation may be undone or the user may choose to come back to results of a specific iteration.

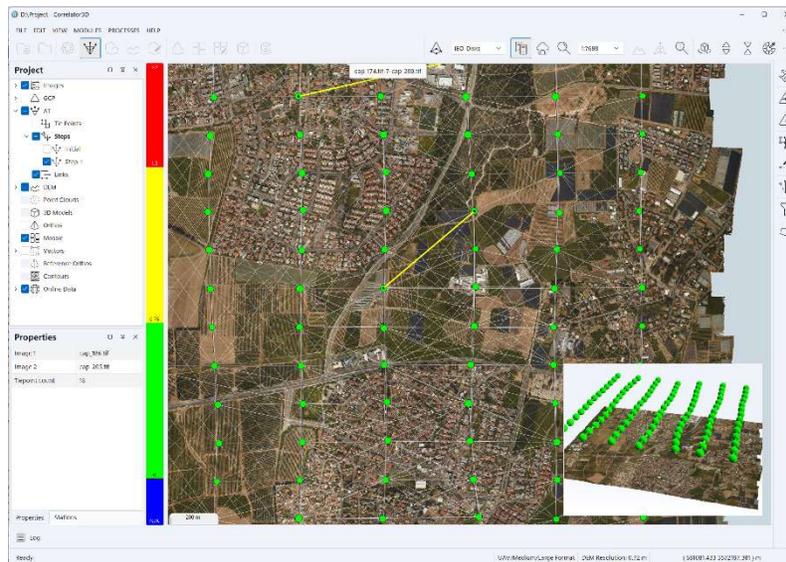


Figure 13: Bundle adjustment results.

To provide the user with feedback, detailed aerial triangulation reports are generated outlining the statistics on all operations performed. The user has access to a general summary, or more detailed reports, such as boresight corrections, image and camera calibration adjustments and tie point, image and GCP residuals. At the end of any AT process, the software automatically displays a PDF report summarizing the statistics as well as the adjustment performed. For convenience, a link to the folder containing more detailed AT reports is also provided at the bottom left corner.

The PDF report can also be accessed from the project tree using the contextual button for a specific bundle adjustment step.

### 7.1.7 Image Filtering



Before continuing with the rest of the photogrammetric workflow, the user should ensure that incorrect images are removed from the project. This will avoid having noise or other artifacts in their results. Therefore, the option to perform “Image Filtering” on the right-hand side is available. This tool creates a new AT step in which images having a tie point residual error higher than the specified threshold will be removed. The user can see the images being filtered in

real-time as the threshold value is modified. Note that this operation can also be done automatically through bundle adjustment using the corresponding setting.

### 7.1.8 Coarse DEM Extraction

 Once all iterations have been performed and the user is satisfied with the results, the updated project can be saved. At this point, the user can create a coarse DEM with the corresponding button. This coarse DEM can be useful if the user wants to assess the quality of the AT. For example, images could be orthorectified using this DEM to make sure that their positions are correct.

## 7.2 DSM Generation

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One of Correlator3D™'s main capabilities is the generation of digital surface models (DSM) from imagery. The software requires overlapping aerial images and GPS/IMU data. The user must specify the desired output horizontal resolution, or simply request the software to calculate an optimal value given the input dataset. This feature takes into account the project parameters (i.e. image resolution, altitude, focal length, etc.) as well as the required processing time and then determines the best compromise. The user can also request the software to calculate the maximal value given the input dataset, or a coarse value for better processing times.

Once a horizontal resolution is specified, the user must select a vertical accuracy from the corresponding slider bar. Lower accuracies will lead to better processing times while higher ones will give the best results, but with longer processing time.

Images are processed pair-by-pair in the order that they appear in each flight line. The required time is thus directly proportional to the number of images. Processing can be performed on multiple machines by taking the exact same project and disabling images through flight lines based on the respective divisions. DSM results can then be merged using the DEM Merging Tool (see Section 11.7).

An optional 3D constraint file can be provided to Correlator3D™. This file can contain points, lines or polygons with elevation (3D) data. Using data values located in the constraint file may result in two benefits. First, it may help the DSM generation process to resolve potential ambiguities, such as occluded regions. Second, it will force the output DSM to have the provided elevation values at the location of the constraining elements.



**If a 3D constraint is provided, Correlator3D™ will force the output values in the DSM to be consistent with the provided constraint. However, if the constraint is not consistent with the rest of the dataset, it may lead to visual artifacts in the DSM. If such a situation appears, the user should make sure that the 3D constraint is in the same coordinate system (e.g. same datum) and that all input data are valid (e.g. camera calibration or exterior orientation parameters).**

The software generates a DSM representing all objects in the scene (terrain, vegetation and man-made structures). However, because of their inconsistent appearance from one image to another, water bodies may lead to noisy DSM regions.

By enabling the corresponding option, users can generate a point cloud that runs simultaneously with the DSM. The software operates not only on a pair-by-pair basis but also searches for adjacent images to enhance precision and provide fully characterized surfaces. The maximum number of observations must be specified, which corresponds to the maximum number of images a feature can be observed in order to triangulate its coordinates. Increasing this number will lead to slightly longer processing times but might increase the precision of some points.



*Correlator3D™ classifies each point in the point cloud based on the number of observations used, up to the specified maximum value. This information can then be used by the “Point Cloud Filtering” tool to filter the point cloud according to the users' needs. By setting the criteria based on the number of observations, users can identify and analyze specific areas of interest with greater precision and accuracy. Please refer to section 11.13 for details.*

Simultaneously, the point cloud can be colorized using the input imagery.

The following steps must be followed to perform DSM generation:

1. Select “DSM generation...” in the “Processes” menu.
2. If a 3D constraint must be used, turn on “3D Constraint”. Note that the constraint file must first be added from the project tree. The constraint will be displayed in the main window overlaid on the DEM.
3. Specify the desired resolution. Press the “Optimal”, “Maximal” or the “Coarse” button to let the program calculate an optimal, maximal or coarse value. Once a resolution is specified, select a vertical accuracy from the corresponding slider bar.
4. If a point cloud is required, turn on “Generate Point Cloud”. Specify the maximum number of observations and check “Colorize Point Cloud” if a colorized point cloud is required.
5. Click on the “Process” button. Real-time feedback will be provided on the overall progress of processing.
6. Save the generated DSM by selecting “Save DEM As...” using the contextual button in the project tree. If a point cloud was generated, save it by selecting “Save Point Cloud as...” using the contextual button in the project tree.

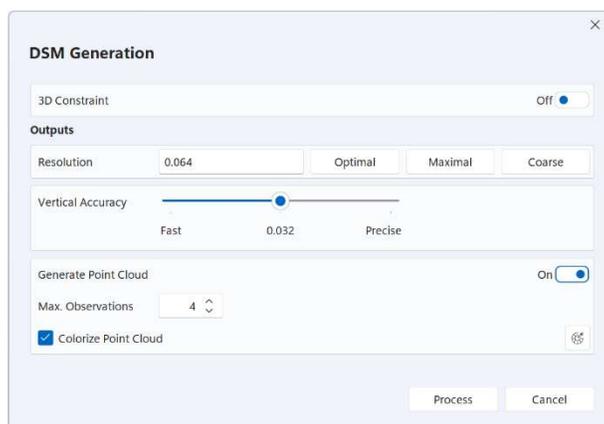


Figure 14: DSM generation dialog.

## 7.3 DTM Extraction

Correlator3D™ features a module to extract a digital terrain model (DTM) from a digital surface model (DSM). Such models are particularly useful for generating orthophotos, as they avoid visual artifacts (e.g. along building edges) caused by using DSMs. The software analyses the DSM and automatically removes structures lying on the ground.

In addition to the input DSM, an optional constraint file can be provided to Correlator3D™. This file can contain points, lines or polygons with elevation (3D) data. It will force the output DTM to have the provided elevation values at the location of the constraining elements. Alternatively, the user has the option to provide an exclusion zone. In such a case, the software will extract the DTM for all areas minus that of the exclusion zone.

 **If a constraint is provided, Correlator3D™ will force the output values in the DTM to be consistent with the provided constraint. However, if the constraint is not consistent with the rest of the dataset, it may lead to visual artifacts in the DTM. If such a situation appears, the user should make sure that the input DEM and 3D constraint are in the same coordinate system (e.g. same datum) and that all input data are valid (e.g. camera calibration or exterior orientation parameters).**

The user can also output into a DEM the features that were removed from the DSM. Note that only the DSM features will appear in that DEM. All other elevation values will be set as undefined.

To create a DTM, follow these steps:

1. Select the DSM you wish to use for DTM extraction from the project tree.
-  2. Select “DTM extraction...” in the “Modules” menu.
3. If a constraint is used:
  - a. Turn on “Constraint”. Note that the constraint file must first be added from the project tree.
  - b. Specify the type. Either "Elevation" or "Exclusion Zone".
  - c. Choose the file containing the constraint using the corresponding drop-down menu. The constraint will be displayed in the main window overlaid on the DEM.
4. If the DSM features are required:
  - a. Turn on “Output DSM Features”.
  - b. Specify the output DEM file using the corresponding drop-down menu.
5. Click on the “Process” button. Real-time feedback will be provided on the overall progress of processing. Once the process is done, the DTM will appear in the main window.
-  6. Save the generated DTM by selecting “Save DEM As...” using the contextual button in the project tree.

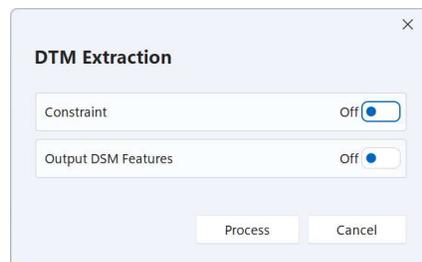


Figure 15: DTM extraction dialog.

## 7.4 DEM Editing

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While the DSM/DTM generation modules produce highly accurate results, the user may still desire to alter results according to their specific requirements. The Correlator3D™ DEM Editing module features ten (10) easy to use, yet powerful editing tools:

- Crop an area
- Delete an area
- Force the elevation to a user-specified value
- Offset the elevation by a user-specified value
- Apply a median or mean filter of user-specified size
- “Delete and fill” i.e. delete an area and analyze neighboring areas to fill the deleted region.
- “Topological Fill” i.e. delete and fill an area while preserving the topology of the neighboring terrain.
- DTM Extraction for a user specified area
- Touch Up small areas
- Paste an external DEM onto the existing DEM

The aforementioned tools process a user-specified polygonal selection. The time required to perform the operations depends on the operation type and the size / complexity of the selection. The user can also display orthorectified images, a mosaic or any other type of reference data as an overlay to the DEM using the project tree. This can facilitate the selection of features like water bodies.

To edit a DEM with a user-defined selection the following steps must be performed:

-  1. Enter the DEM editing module, by selecting “DEM Editing...” in the “Edit” menu. The editing toolbar will appear at the right of the window.
2. Create a selection.
3. Select an operation to perform in the Edit menu or the DEM Editing toolbar.
4. Repeat step 2 and 3, as required
-  5. Save the edited DEM by selecting “Save DEM As...” using the contextual button in the project tree.

There are three modes of selection that are mutually exclusive:

- Standard selection
- Append a selection
- Touch up

### 7.4.1 Standard Selection

 The standard selection is the most common way of selecting an area for editing. It is used when several operations need to be performed sequentially on several locations. A new selection can be created at any time by clicking on the left mouse button. Doing so automatically deselects the previous selection and starts a new one. Additional left-clicks are necessary to make the selection. To close the selection, the user must click in the vicinity of the initial point or simply right-click.

 A rectangular selection can also be created in a similar manner. The user simply needs to drag the selection onto the DEM.

During a selection, pan operations are supported using the middle (wheel) mouse button. Placing the cursor at the edge of the display area automatically pans the DEM.



**Note that zoom operations are not permitted during a selection.**



*Correlator3D™ supports single non-self-intersecting polygonal selections. As such, Correlator3D™ will refuse to add a point to or close the selection if it makes the polygon to self-intersect.*

When the selection is finalized, a contextual toolbar is displayed on the top left corner of the main view. With this toolbar, the user has the option to edit the selection with different tools before doing an operation on the region.



The first one, the hand tool, is used to move, add, or delete selection points. A point can be moved by clicking on its vicinity with the left button of the mouse and dragging it at a new location. Conversely, it can be removed by clicking on the right button. New points can be added by clicking on the right button of the mouse anywhere on the selection.



*Depending on the scale factor, Correlator3D™ will adjust automatically the level of details of the selection. Therefore, if the user zooms in the selection, additional selection points will be shown.*



The second tool, the scissors tool, is used to remove a series of selection points and replacing them with new ones. A first point must be selected with clicking on the left button of the mouse, and then a second one to determine the series of points to be removed. New points can then be added to follow a new path, starting from the last point to the first one.



Note that elevation values for each vertex of the polygon can also be manually set. Use this function to select any vertex and change the elevation value.



The last operation on a selection can always be undone by pressing the corresponding button in the mosaic editing toolbar or using the keyboard shortcut “Ctrl-Z.”



Correlator3D™ also offers automatic tools to modify a selection. If instead of a polygonal selection the user wishes to select a feature, the Feature Selection option should be used. This option will snap automatically to the boundary of the feature contained within the original selection. The user has then the option to edit the selection by moving existing points or creating new ones.



The user can also snap the selection based on elevation values. This is particularly useful to select undesired spikes or other features to be removed quickly. When clicking on this button, a dialog will be displayed to select the criteria to be used to snap the selection. For example, the user could choose to select everything above a certain elevation.

 Once the selection is completed, the user can either select the DEM operation to perform, or save the selection before by clicking on the “Save Selection” button from the contextual toolbar, or by using the “Enter” keyboard shortcut.

 A selection can also be cleared by clicking on the “Delete Selection” button from the contextual toolbar or by using the “Escape” keyboard shortcut.

 Finally, if the user wants to edit the selection after saving it, clicking on the selection will bring back the contextual toolbar, and editing will be possible. Clicking the “Discard Changes” button will bring back the original selection.

### 7.4.2 Save a Selection to Disk

 Once a selection has been created, the user can save it by clicking the “Save Selection” button from the DEM Editing toolbar. The new feature file will be added automatically to the project tree, allowing the user to save the selection to disk (by using the corresponding contextual button next to it). This can be particularly useful if the same selection has to be used with several DEMs. It can also be used to define exclusion zones or other types of constraint that can be used during other processes like the DTM Extraction. Note that this step is also required if multiple selections need to be defined.

### 7.4.3 Edit Feature File

 Once a feature file has been created, the user can toggle the “Edit Feature File” mode to modify or append other selections to the file. This can be particularly useful if the same operation has to be applied simultaneously on several locations.

This mode provides the exact same functionality as the Standard Selection, meaning that a contextual toolbar will be displayed for each new selection that is being appended. The user can click on the “Save Selection” button from the contextual toolbar to add this new selection to the file. Note that, just like in the “Standard Selection” mode, it is always possible to edit one of the selections by clicking on it.

### 7.4.4 Touch Up

 The Touch Up tool works in a similar manner than the Delete and Fill tool. Instead of requiring a manual polygonal selection, a small fixed-size square selection is automatically performed around the location clicked by the user. The tool requires less user interaction and the internal processing is optimized for higher performances. Thus, it is a very fast tool to correct small areas.

### 7.4.5 Crop

 Correlator3D™ features a polygonal crop tool. Once a polygonal selection is made, the Crop tool will discard any elevation values outside the selection. The DEM will also be resized to fit the size of the bounding box of the selection. To use the Crop tool, select “Crop” from the “Edit” menu.

### 7.4.6 Delete



The Delete tool discards all elevation values inside the selection, leaving any other value intact. To use the Delete tool, select “Delete” from the “Edit” menu.

### 7.4.7 Set Elevation

The Set and Offset Elevation tools are accessible from the same dialog.

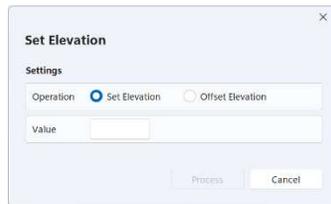


Figure 16: Set and offset elevation dialog.

The Set Elevation operation sets the selected DEM cells to the specified elevation, while the Offset Elevation operation offsets the selected DEM cells by the specified elevation. The elevation can be a positive or negative value and is specified in the DEM units (meters or feet).



To use the Set Elevation or the Offset Elevation tool, select “Set Elevation...” in the “Edit” menu.

### 7.4.8 Filter

The filter tool applies a mean or a median filter to the selected DEM cells. Cells outside the selection and cells located on the border will be used to compute filtered elevation values. However, these cells will remain unaffected by the process. Settings can be adjusted using a dialog.

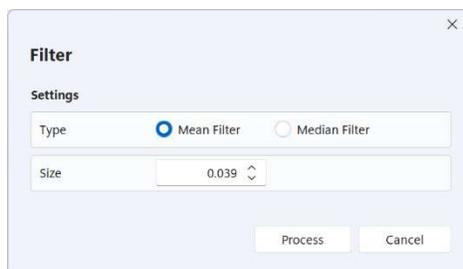


Figure 17: Filter dialog.

The following is a description of the required settings:

**Filter Type:** Decides between mean and median filters.

**Filter Size:** Diameter of the filter, specified in DEM units (meters or feet). The specified value must be an odd multiple of the DEM resolution.



To use the Filter tool, select “Filter...” in the “Edit” menu.

## 7.4.9 Delete and Fill



Delete and Fill is probably the most useful and powerful editing tool provided by Correlator3D™. With a single click, all the selected DEM cells are deleted and replaced by new elevation values obtained from an analysis and interpolation of the area surrounding the selection. It requires no parameters to be specified and provides excellent results in most situations. To use the Delete and Fill tool, select “Delete and Fill” from the “Edit” menu.

## 7.4.10 Topological Fill



The Topological Fill tool provides similar functionality to the Delete and Fill tool, except that it analyzes the topology of the neighboring terrain to better interpolate the area. For example, it can be used to remove a feature located on a slope. To use the Topological Fill tool, select “Topological Fill” from the “Edit” menu.

## 7.4.11 DTM Extraction



The DTM Extraction tool extracts the DTM for the selected DEM cells. It uses the same algorithms than the DTM extraction process and settings can be adjusted using a similar dialog. Please refer to Section 7.3 for further details. To use the DTM Extraction tool, select “DTM Extraction” from the “Edit” menu.



Figure 18: DTM extraction dialog.

## 7.4.12 Paste DEM



The Paste DEM tool replaces regions of the current DEM with a provided DEM. The user can adjust the height tolerance parameter that defines the difference in height between the two DEMs for which a smooth transition will be calculated. Hence, elevation values showing a difference smaller than this value will be averaged in the final DEM. To use the Paste DEM tool, select “Paste DEM” from the “Edit” menu.



*The Paste DEM tool will not consider any current selection as the input DEM will be pasted entirely.*

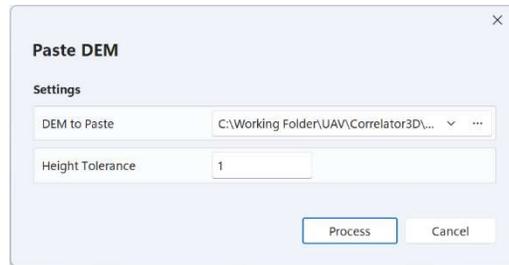


Figure 19: Paste DEM dialog.

### 7.4.13 DEM History (Undo/Redo)

The history of each modification made to the DEM is automatically saved. This history is displayed below the project tree as a list of all operations that were performed to the DEM. Clicking on one of the operations will undo all subsequent operations. To better guide the user on what operations should be undone, Correlator3D™ provides the following visual feedback: hovering the cursor above any item of this list will display all the modified regions so far as an overlay to the DEM. Regions shaded in blue with a number in it correspond to the regions that will not be affected by the “Undo” operation if the user clicks on this item. Regions shaded in red correspond to regions for which the modifications will be canceled. Note that it is always possible to redo the operations if no operation is made after the undo.

## 7.5 Orthorectification

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Correlator3D™ can generate orthorectified images. The user can specify the desired output resolution, or simply request the software to calculate the optimal or coarse value for better processing times. This feature automatically determines the ground sampling distance (GSD) of the input imagery.

Correlator3D™ can generate true orthos if a DSM and/or a constraint file is used. In such a case, the orthorectification process will correct for the distortion of buildings and other 3D structures, resulting in a true ortho. Occluded areas which have no image content, e.g. building shadows, will be set to black in the final orthorectified image. Note that if a constraint file is inputted, it must contain polygons with elevation (3D) data defining the structures.

For frame-based sensors, the user can also specify the overlap of the resulting orthophotos. By default, the software will suggest the maximal overlap, i.e. the actual overlap between images. The user can also select the optimal overlap, which corresponds to 30%.



*Choosing a smaller overlap will result in a faster orthorectification, smaller orthophotos on disk and ultimately faster mosaic creation. Note however that reducing the overlap between orthophotos will also reduce the area where a mosaic seamline can go through and may therefore impact results.*

For UAV/medium/large format sensors, the user can crop the image borders to any percentage value. This allows for forward and sidelap control, which may be desirable as a strategy to extract

the most nadir image portion from the orthophoto, or to remove artifacts that are systematically present in all images.

For multispectral cameras, the user has the option to calculate reflectance information for each image and add it to the resulting orthophotos. This information will be used afterwards when creating a mosaic from the orthophotos, and when finally exporting a reflectance map. The reflectance information can be calculated using calibrated data that come either from a sun sensor, or calibrated reflectance panels, or both. Please refer to section 11.5 for further details about calibrated reflectance panels.



**The output format of the orthorectified images is by default tiled with overviews. This should not be changed if the user prefers using the Mosaic Editing module afterward to obtain the highest performance.**



*Since orthos can sometimes take significant disk space, the user has the option to store them as JPEG-compressed TIFFs. While this type of compression is not lossless, the quality of the orthos will not be significantly affected. An additional band will also be added to the orthos to store the validity of each pixel for mosaicing.*

A real-time overview of the orthophotos will be displayed during processing. Each time an orthorectified image is generated, it will appear as an overlay to the currently loaded DEM.

To create orthorectified images, the following operations should be performed:



1. Select the DEM you wish to use for orthorectification from the project tree.
2. Select "Orthorectification..." in the "Processes" menu.
3. If true orthorectification is required and a DSM is loaded, turn on "DSM-based".
4. If a 3D constraint file is used, turn on "Constraint File". Note that the constraint file must first be added from the project tree. The constraint will be displayed in the main window overlaid on the DEM.
5. Specify the desired output horizontal resolution or press the "Optimal" or "Coarse" button to let the program calculate an optimal or coarse value.
6. In the "Settings", select "Overlap" to specify the desired output overlap percentage. Press the "Optimal" or the "Maximal" button to let the program calculate the optimal or maximal value. To crop the image width and height, select "Crop" and specify the desired percentages.
7. If the camera is multispectral and reflectance information needs to be calculated, check "Use Calibration Panels" or "Use Sun Sensor", or both.
8. Specify the format for the orthorectified images.
9. Click on the "Process" button. Real-time feedback will be provided on the overall progress of processing.

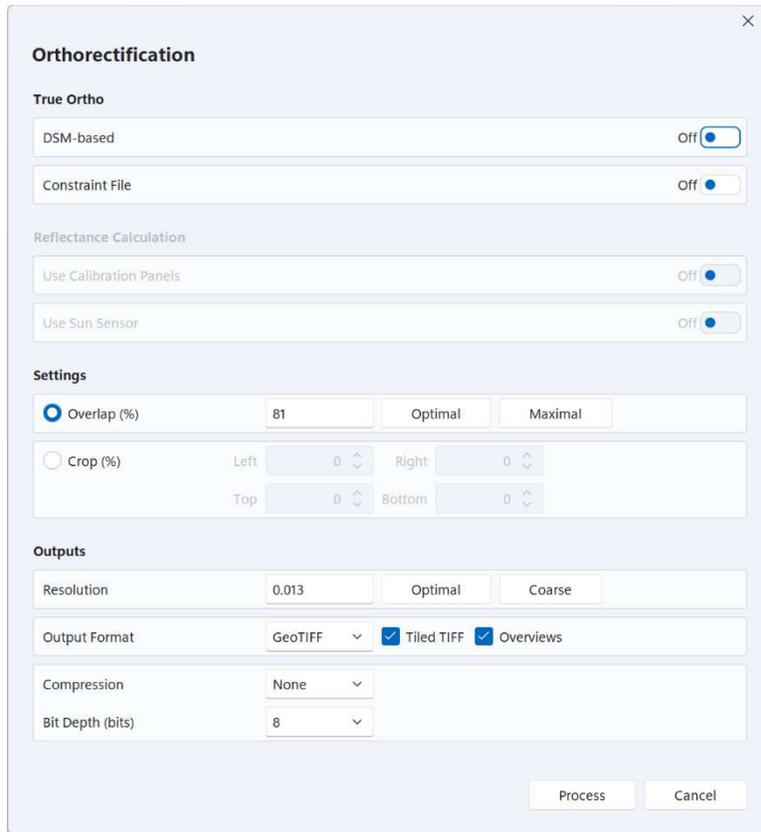


Figure 20: Orthorectification dialog.

## 7.6 Mosaic Creation

The mosaic creation module allows for the merging of individual orthorectified images to obtain a unique image covering the entire project area. The process is entirely automated. Correlator3D™ will select which portion of which image must be included in the final mosaic. Local intensity adjustments and seamline generation are performed to provide smooth and seamless transitions between adjacent images composing the mosaic.

Before starting the mosaic operation, the user can specify how many blocks to divide the mosaic into at minimum. A block is a smaller section or part of the overall mosaic. The purpose of this is to support the generation of large mosaics but also to allow multiple users to edit different blocks simultaneously after the mosaic has completed. The number of blocks is therefore dependent on the user's choice and project size. The software will create the blocks according to the user's selection, but may need to perform further block divisions as necessary.

Selecting the Bound Mosaic Area option allows to generate a mosaic for only a portion of the project, as defined by a user created polygons stored in a tile definition file or a Shapefile. The user can also specify the size of the feathering zone depending on project type. The feathering zone is the region along a seamline where blending will be applied to ensure a smooth transition from one image to the other. For urban areas, a smaller value is recommended in order to avoid ghosting effects along smaller objects like cars. In other areas like open fields, the value should be larger since the content is very similar from one image to the other. The size of the feathering zone is

specified in pixels. Note that when editing a mosaic, a different value can be specified for each seamline.

Fully automated color balancing can be applied during the mosaic creation process. This balancing includes:

- Brightness and contrast adjustments of each image
- Inter-image equalization
- Independent channel analysis for hue equalization
- Photometric constraints to maintain global information of brightness, contrast and hue

Some projects may include regions where colors are very different from one image to the other (e.g. water bodies). In order to avoid these regions to have too much effect on the color balancing results, the user can specify an exclusion zone. This file can contain several polygons depicting the regions to be ignored.

To profit from the most nadir portion of the orthophotos, the user can select the "Nadir Optimization" option. This allows improving the overall mosaic quality while increasing processing speed. Note however that it will reduce the size of areas where seamlines can be calculated and moved during mosaic editing.

To further improve the quality of the seamlines and make sure they wave around obstacles, the user can select the "Use Loaded DEM for Seamline Obstacle Avoidance" option. The process will then consider the currently loaded DEM (generally a DSM), in addition to all other mosaicing algorithms, to compute the optimal seamlines.

The output of the mosaicing process consists of a single image divided in multiple blocks, themselves divided into multiple tiles. Files required to manually edit the mosaic seamlines and colors are automatically generated during mosaicing and are stored in subfolders to the mosaic folder. The software has therefore its own structure to store the files. Users who desire to specify their own mosaic tiling and format have to export the mosaic. This functionality is described in section 11.9.

To create a mosaic, follow these steps:

- 
1. Make sure the project includes orthos.
  2. Select "Mosaic Creation..." in the "Process" menu.
  3. If only some portions of the orthos need to be mosaiced, turn on "Bound Mosaic Area" and specify the file using the corresponding drop-down menu.
  4. Specify the size of the feathering zone in pixels.
  5. Specify the minimum number of blocks.
  6. If color balancing is required, turn on "Color Balancing".
  7. If an exclusion zone is specified, check "Exclusion Zone File" and specify the file using the corresponding drop-down menu.
  8. If nadir optimization is required, turn on "Nadir Optimization".
  9. Turn on "Use DSM to Constrain Seamlines" if seamlines need to be further improved. Make sure the corresponding DSM is currently loaded in the user interface.
  10. Click on the "Process" button. Real-time feedback will be provided on the overall progress of processing.

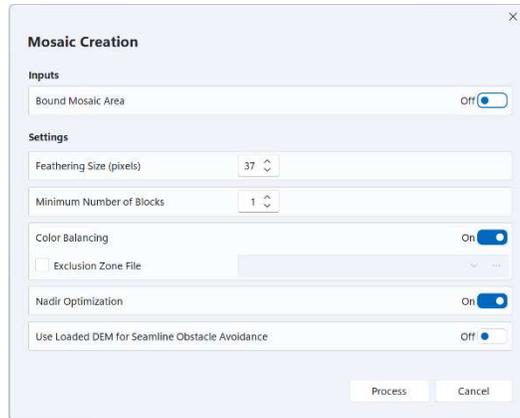


Figure 21: Mosaic creation dialog.

## 7.7 Mosaic Editing

The mosaic editing module allows the auto-generated mosaic to be interactively adjusted according to specific user requirements. It provides a smooth interaction with the data and allows real-time updating during modifications, without having to regenerate the entire mosaic completely. This design reduces the number of manual operations required, significantly increasing the overall productivity.

Correlator3D™ also allows for limitless users to simultaneously edit a mosaic without conflicts or duplication of any data. Therefore, multiple users can access the same mosaic location, reducing significantly storage requirements and leading to fast and efficient operation suited to production environments.

To edit a mosaic, please follow these steps:

1. Make sure the project includes a mosaic and the orthos used to generate this mosaic.
2. Select “Mosaic Editing...” in the “Processes” menu. The mosaic and the corresponding blocks will then appear in the main window.

Upon entering mosaic editing mode, users are presented with a view of the entire mosaic and a block overlay. The block overlay reveals how the mosaic is split up. This view enables users to apply global operations to the entire mosaic area including exporting seamlines, exporting the mosaic and manually adjusting the colors.

Users can also edit the auto-generated seamlines by selecting which block(s) to work on. Blocks are selected by clicking on them. While each mosaic block can be edited by a single user, different mosaic blocks can be edited simultaneously by multiple users. In order to provide multiple users seamline editing capability, Correlator3D™ provides an automatic locking system. Blocks already in use cannot be selected and will be shaded in red to indicate they are locked by another user. Otherwise, if no blocks are in use, then they will all be shaded in green to indicate they are available.



*Please note, while users do not need to manually select them, all blocks must be available (i.e. not locked) to export seamlines, export the mosaic or manually adjust colors.*

### 7.7.1 Export Seamlines



Users can export the seamlines to an ESRI Shape file by pressing the corresponding button in the toolbar.

### 7.7.2 Adjusting the Colors



Users can adjust the global colors of the mosaic using the Color Adjustment tool to enhance its visual appearance. This tool allows modifying the levels of the mosaic, i.e. making adjustments to the brightness, contrast, and gamma for each individual b or for all channels together.

In the Channel drop-down list, users can select a color channel to edit. Depending on the number of channels of the imagery, users can choose the "Master" channel to edit the red, green, blue and alpha channels all together, or choose "Red", "Green", "Blue" or "Alpha" to edit the channels individually. Note that selecting the "Alpha" channel will also allow users to display this channel in the main window. For grayscale mosaics, only one channel can be selected.

The original histogram of the mosaic for the selected channel is displayed in blue in the dialog, while the new histogram to be applied is overlapping in red. A preview of the adjusted mosaic is displayed on the mosaic in the main window. This option can be toggled at all times in the color adjustment dialog.

To increase the contrast of the image, users must drag the input levels sliders, which show the image's brightness values. To darken the darkest values, the left slider must be dragged to the right; all values below this value become zero (black). To lighten the lightest values, the right slider must be dragged to the left; all values above this value become 255 (white) or 65,535 for 16-bit imagery. To change the value of medium grey, the gamma slider must be dragged left or right; the range for of the gamma value is 0.1 to 10.0, with 1 being in the middle.

To decrease the contrast, users must drag the output levels sliders. To lighten the darkest pixels, the left slider must be dragged to the right. To darken the lightest pixels, the right slider must be dragged to the left.



*For 16-bit imagery, users can activate the "Stretch" mode of the main window. Doing so when the Color Adjustment dialog is displayed will automatically stretch the histogram of the Master channel and therefore provide a quick way of adjusting the colors over the 16-bit range.*

Adjustments to the mosaic on disk will not be applied until the "Process" button is clicked. Note that once the process is started, it cannot be stopped since all mosaic tiles on disk must be adjusted with the same parameters.



*Adjusting the colors on a multispectral mosaic for which reflectance information was calculated during orthorectification will automatically remove this information.*



Figure 22: Color adjustment dialog.

### 7.7.3 Seamline Editing Mode



After the blocks to be edited have been selected, press the "Seamline Editing" button to enter Seamline Editing Mode.



Note that users can toggle back to the mosaic overview to select different blocks by pressing the "Block Section" button.



*To ensure smooth operation and to minimize memory requirements, it is recommended to select the fewest blocks possible when entering into seamline editing mode.*

There are two viewing modes in which users can interact with the project. In both modes, users can zoom in, zoom out or pan the images the same way they interact with a DEM. The first mode displays the chosen blocks and the corresponding seamlines and is used to visually inspect this mosaic section and locate seamlines to be edited.

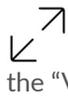
The second mode is used to edit a particular seamline. Users can access this mode by clicking on the seamline to be edited. Correlator3D™ will then load the images corresponding to each side of the seamline. One side is displayed as a bright image and corresponds to the mosaic region that was generated prior the addition of the new orthorectified image. The other side is displayed as a dark image and corresponds to the new orthorectified image that is being added to the mosaic. The overlap region between both images is displayed with the original color.



*In order to accelerate the loading time, only orthorectified images corresponding to the current view region are displayed. Therefore, when editing a seamline, some images may be missing if users pan outside the region.*

Correlator3D™ displays seamlines according to a particular color scheme. A color is assigned to each segment of a seamline depending on its quality, i.e. as determined automatically during the mosaic creation. If the software is confident that the seamline follows a path that minimizes the artifacts in

the final mosaic, it will be green. If not, its color will be red and if the confidence level is in between, the seamline will be yellow. Note seamlines that have been previously edited will be blue. Users can therefore rely on the color scheme to have a first appreciation of the mosaic and determine which seamlines should be edited first.

 For 16-bit imagery, users can also stretch the histogram to improve brightness and contrast during mosaic editing. It can be enabled or disabled by selecting “Display Style->Stretch” in the “View” menu. Note that enabling this mode will not modify the colors of the mosaic on disk.

 Users can also display the mosaic tile definition by toggling the corresponding button. The name of each tile as well as its boundaries will be displayed as an overlay to the mosaic. If a tile overlay was not provided by the user, then this option will instead display the software's own internal tile definition for the blocks.

#### 1.1.1.1 Interacting with Seamlines

Once a seamline has been selected, users can modify its path using two different tools. These tools can be accessed by clicking on their corresponding buttons in the mosaic editing tool bar or from the edit menu. Users can also switch from one tool to the other by pressing the “Tab” key on the keyboard.

 The first one, the hand tool, is used to move, add, or delete seamline points. A point can be moved by clicking on its vicinity with the left button of the mouse and dragging it at a new location. Conversely, it can be removed by clicking on the right button. New points can be added by clicking on the right button of the mouse anywhere on the seamline.

 *Depending on the scale factor, Correlator3D™ will adjust automatically the level of details of the seamlines. Therefore, if users zoom in the seamlines, additional seamlines points will be shown.*

 The second tool, the scissors tool, is used to remove a series of seamlines points and replacing them with new ones. A first point must be selected with clicking on the left button of the mouse, and then a second one to determine the series of points to be removed. New points can then be added to follow a new path, starting from the last point to the first one.

 *When moving points of a seamline, a red region is displayed around the seamline. This region corresponds to the feathering zone, i.e. the region where a progressive transition is made between an image and another. Users should take into account this region when defining the path of a seamline since it may result into blurry results in the final mosaic. For example, the feathering zone should not pass nearby an object if this object does not appear in both images.*

 *When modifying the path of a seamline, Correlator3D™ will automatically update the image to represent what the mosaic should look like, without feathering and color balancing being applied.*



If there is a seamline traversing multiple blocks, then only the section of the seamline in the currently loaded blocks will be available for editing. Furthermore, modifying the point at the boundary of the block will not be possible. Likewise, changing the feathering size will not be possible unless all the blocks containing the seamline are loaded.



The last operation on a seamline can always be undone by pressing the corresponding button in the mosaic editing toolbar or using the keyboard shortcut “Ctrl-Z.”



Users can also modify the size of the feathering zone for a specific seamline. Once the new size has been set, it will first modify the size of the red region that is displayed around a seamline when moving its points. Note that modifying the size of the feathering will have a great impact on the processing time when updating the mosaic since it has to be applied on its full length. Also note that the new size only affects the currently selected seamline, and that a different size can be specified on every seamline.



Note, the feathering size can only be changed for an entire seamline. Hence, if a block contains only part of that seamline, then the feathering size cannot be adjusted. Users will need to load all blocks containing a seamline in order to change its feathering size.

The following table summarizes the keyboard shortcuts that can be used when editing seamlines.

Action	Keyboard Shortcut
Undo the last operation on a seamline	Ctrl-Z
Change current editing tool	Tab
Save modifications to a seamline	Enter
Discard modifications to a seamline	Esc

Table 5: Keyboard shortcuts for mosaic editing.

### 1.1.1.2 Updating the Mosaic



Once users are satisfied with a seamline, modifications must be saved by pressing the corresponding button in the mosaic editing toolbar or the keyboard shortcut “Enter”. The display will then automatically switch back to the mosaic viewing mode. Each modified segment of the seamline will be displayed in blue, and the region of the mosaic that will be affected by the modifications will be highlighted in cyan.



Users can then update the mosaic by pressing the corresponding button in the mosaic editing toolbar. Correlator3D™ will only process the new region, with feathering and color balancing being applied. This functionality removes the necessity of regenerating the whole mosaic and allows users to get the final result in a matter of seconds.



Modifications of a seamline can also be discarded by pressing the corresponding button in the toolbar or the keyboard shortcut “Esc”. The display will then automatically switch back to the mosaic viewing mode with the original seamline being displayed.

### 1.1.1.3



On larger projects, it becomes essential to determine which line has been inspected or modified to avoid duplicating efforts. It is therefore strongly recommended to use

the Mark/Unmark functionality to keep track of what has been done so far. Using the selection tool, the user can first select the seamlines that are completed and press the “Mark” button. This will result in changing the seamline color to black. Conversely, a seamline can be unmarked by toggling the same button. This button is also available when editing a particular seamline.

## 7.8 3D Model Generation

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Correlator3D™ can generate photorealistic 3D models. In a standard workflow, the process will create a mesh from a DSM, then uses input images to texturize it. Other processing scenarios are possible. For example, if an existing 3D model is selected from the project tree, this model will be used as a seed: the mesh will remain the same or will be simplified to meet the new size requirement. If the “Generate Texture” option is selected, a new texture will be generated.

One important aspect of a 3D model is its size. For standard third-party 3D viewers, the 3D model that is loaded must fit entirely into the memory of the GPU for visualizing it smoothly. As a result, Correlator3D™ provides a slider bar for the user to choose the size. A coarse 3D model will take a minimum of resources when viewing it, but will contain less mesh complexity and texture details. Conversely, a 3D model with a maximum size will have a greater workload on the GPU but should have more quality. The user can choose the size of the resulting 3D model using the slider bar, or ask for the “Optimal” value, which corresponds to a compromise between quality and size. Note that the range of the slider bar will be adapted to the available GPU memory on the computer used for processing.

Depending on the selected options, the “Notes” section of the dialog will be updated to provide a precise description of the process and its expected outputs. It will indicate which model is going to be used as an input to the process (a DSM or a 3D model), the approximate number of triangles in the final mesh, the number and size of the texture files (if a texture is to be generated), and finally the expected GPU memory workload of the resulting 3D model.

The following steps must be followed to perform 3D model generation:

1. Select a DSM (or a 3D model) from the project tree.
2. Select “3D Model Generation...” in the “Processes” menu.
3. If a mesh needs to be created from the DSM, turn on “Create Mesh from DSM”. Otherwise, the mesh from the current 3D model will be used as an input.
4. If textured is required, turn on “Generate Texture”.
5. Specify the model size using the corresponding slider bar. Press the “Optimal” to let the program calculate an optimal value.
6. Click on the “Process” button. Real-time feedback will be provided on the overall progress of processing.
7. Save the generated 3D model by selecting “Save 3D Model As...” using the contextual button in the project tree.

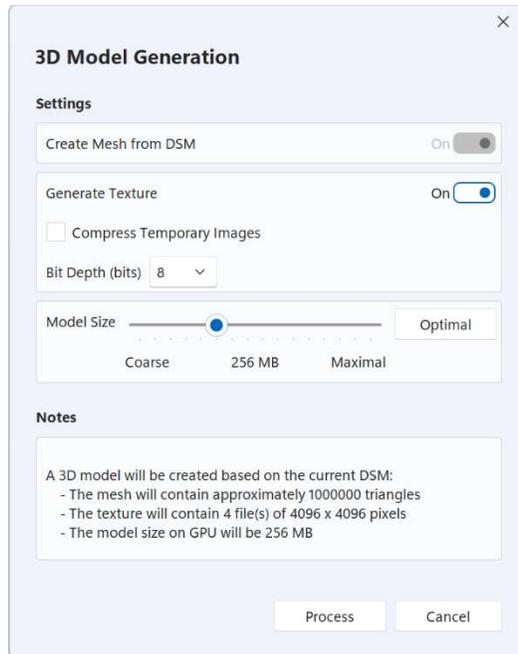


Figure 23: 3D Model generation dialog.

# 8

## AUTOMATED WORKFLOW

The automated workflow is an automatic solution to the Correlator3D™ data production process. This tool is used to perform the complete Correlator3D™ workflow:

- Aerial Triangulation
- DSM Generation
- DTM Extraction
- Orthorectification
- Mosaic Creation
- 3D Model Generation

To start processing, the user must first select a processing profile. Five profiles are available corresponding to common processing needs:

- **Quick Project Overview:** generates all outputs at coarse resolutions.
- **True Ortho:** generates all outputs at optimal resolutions and a true orthomosaic.
- **Classic Photogrammetric:** generates all outputs at optimal resolutions and a DTM-based orthomosaic.
- **Fast Ortho:** generates coarse DEM and an orthomosaic at an optimal resolution.
- **3D Model:** generates a 3D model.

Each profile has its own set of parameters and options. For specific requirements, the user can customize the options of a profile. It is important to note that each processing step is optional. By simply selecting or de-selecting a checkbox, the user can perform desired actions. For example, the user can start the automated workflow from DTM up to mosaic by using only the appropriate toggle switches.

When selecting the “Generate script”, the user can create a script with the chosen actions and parameters and skip the processing. The script is saved to a text file (Project.spt) in the project folder. This script can then be adapted to specific requirements, where other variables and parameters can be changed from the default settings. The user can then execute the script from the file menu. Further details can be found in section 0.

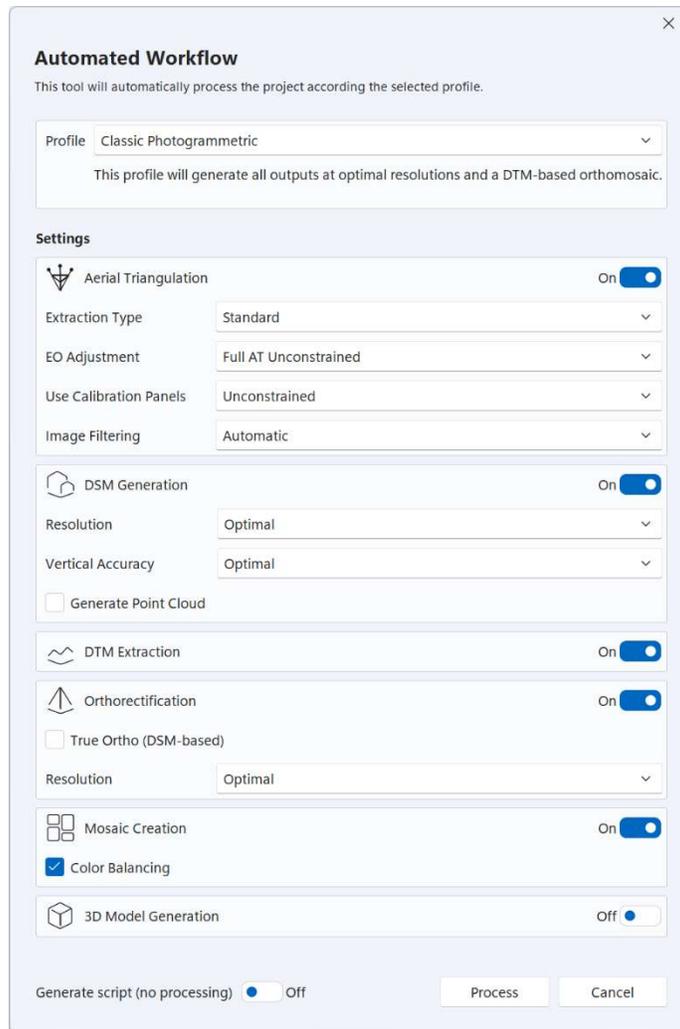


Figure 24: Automated workflow dialog.

# 9

## FEATURE EXTRACTION

The feature extraction module enables the user to extract 3D features from a DSM by creating 3D polygons. Automatic contour detection of buildings and other features enable fast footprint collection. Intelligent analysis aids the user while editing features, using the 3D information in the DSM to automatically calculate how well planes fit the segmented polygon and providing visual feedback. Feedback can also be provided through real-time true orthorectification to achieve pixel accuracy. This semi-automatic design saves time over traditional vector extraction methods.

To extract features, the following operations should be performed:



1. Select the DEM you wish to use for feature extraction from the project tree.
2. Select "Feature Extraction..." in the "Mode" menu.
3. Turn on the Edit/Append box to edit an existing vector file. Specify the vector file using the corresponding drop-down menu. The vector file must be an existing ESRI shapefile containing 3D information.
4. Turn on the "Real-time True Ortho" box to enable this feature. Specify the DTM file using the corresponding drop-down menu.
5. Click on the "Process" button to start extracting 3D features. The resulting vector information will be saved in a new vector file once the user chooses the save option in the feature extraction menu.

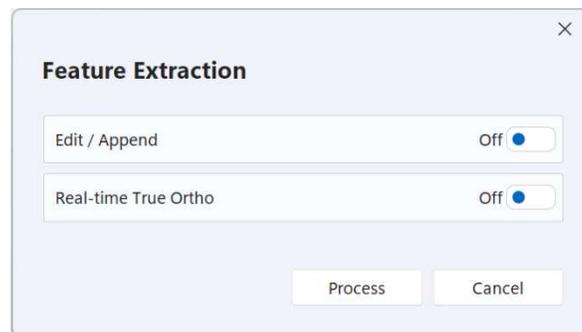


Figure 25: Feature extraction dialog.



*If loading an existing vector file containing building footprints, the user will need to select/edit each building to assign a 3D polygon.*

### 9.1 Extraction Modes

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There are four modes in which the user can interact with the DSM. These four modes are based on feature type which includes buildings, roads, water bodies and forests. The default mode is buildings. The user can switch modes by clicking on the Process menu and selecting the mode of choice.

### 9.1.1 Building Extraction Mode



Should the user wish to extract buildings must first ensure they are in the building extraction mode. A building is selected in 2 steps. First, pan and zoom to the area of interest. Second, make a rough selection around the building by clicking around the building perimeter. The software will automatically squeeze the selection around the contour of the building as shown in Figure 26.



The user can go back to the original selection by selecting "Undo" in the "Edit" menu.

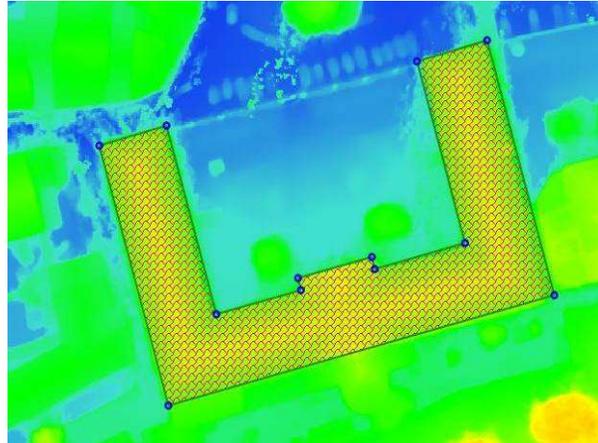


Figure 26: Contour around a building.



The user then has the option to modify the contour according to their requirements using the hand tool. The hand tool is used to move, add, or delete points. A point can be moved by left-clicking and dragging it to a new location. Conversely, it can be removed by right-clicking with the mouse. New points can be added by right-clicking anywhere on the contour.



Holding the control (Ctrl) button while moving a line segment will restrict the movement of that segment in such a way that the line segment moves either in a direction parallel to itself or in a direction along itself (collinear with itself). A special case occurs when moving an interior line segment contained within the building footprint. In this case, the line segment will also resize itself to fit within the building footprint. Note, however, the line segment may not resize itself if the building footprint is irregular.



The edge merging option is enabled by default. When enabled, edges will be merged as long as they are collinear and represent the same line.



When using the hand tool to add a point, that point may "disappear" if it was added to a straight line. This is because the edge merging tool is enabled. The edge merging tool "sees" this point as splitting a line segment into two collinear line segments and consequently merges them. Hence, the edge merging tool should be disabled to split a straight line into two parts.



All angles of a selected building contour that approach ninety (90) degrees can be rectified. The rectify operation changes these angles to be as close to ninety (90) degrees as possible.



The software automatically extracts 3D information from the DSM and determines the z-value of each vertex of the polygon bounded by the contour. The polygon starts off as a plane representing the building. In most cases a building's roof is more complex than a plane. For these situations, the "Add a surface" tool can be used to add further details to the building polygon. The 'Add a surface' tool is used to segment the building polygon into more planes to better represent the roof geometry. To segment the plane, left click and hold on any contour line of a building and drag the mouse to see a dotted line indicating the plane segmentation as shown in Figure 27.

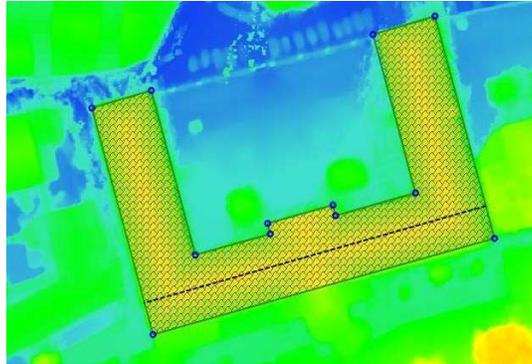


Figure 27: Plane segmentation indicated by the dotted line.

The newly created dotted line indicates the building polygon is divided into two sections. The software automatically recalculates the new plane to be applied to each section and determines the z-value of each vertex. It uses the 3D information in the DSM for this calculation. The fact that the line is dotted indicates that the two new planes touch at their boundaries (e.g. two planes that create a roof slope). If the line was solid it would indicate that the boundary of one plane meets the other plane in an area other than the boundary, creating a discontinuity in elevation (e.g. when a small building is connected to a taller building). In other words, the software automatically uses the building contour (the outer most border of the building) and the dotted/ solid lines to fit planes within those boundaries. The user should segment the building polygon to create as many planes as necessary to represent all the various slopes in the roof geometry of a particular building.

In addition to segmenting planes by clicking on the edges, points can likewise be dragged to divide the polygon into different slopes. New points can also be added by right-clicking on the feature lines.



If the surface merging option is turned on, planes that are coplanar and that represent the same surface will be automatically merged together as the user is modifying the building.

Visual feedback is provided based on how well planes fit within their surfaces. In particular, as the user is segmenting the polygon to better define roof geometry, the software automatically calculates how well a particular surface can be represented by a single plane. If a plane poorly represents a surface, then that plane is shaded red. Likewise, if a plane represents a surface only marginally well, then it is shaded yellow. Otherwise, the plane fits a surface well and is shaded green.



The best fit function uses the information in the DSM to improve the position of the planes. The criterion for moving vertices is based on which configuration will result in the best fit for the planes. Note this might not necessarily correspond to the best visual positioning of the contour. If the position of the points is already optimal, then the best fit function will not perform any further changes.



Note that elevation values for each vertex can also be manually set. Use this function to select any vertex and change the elevation value.

### 9.1.2 Road Extraction Mode



This mode allows the user to extract road features. The user traces out the road using the mouse. For each vertex of the polygon, the median elevation within a fixed boundary inside the polygon is taken as the road height. This accounts for any banking or slopes the road may traverse.

### 9.1.3 Waterbody Extraction Mode



This mode allows the user to extract water surfaces. The user traces out the water boundary using the mouse. For each vertex of the polygon, the median elevation within a fixed boundary outside the polygon is taken as the water height. This means that there must be some ground clearing around the waterbody in order for the polygon to take on appropriate values.

### 9.1.4 Forest Extraction Mode



This mode allows the user to extract forests. As in building extraction, this mode uses contour fitting. Hence, the user needs only to make a rough selection around the forest area and the software will automatically squeeze the selection to the forest boundary. The elevation applied will be a local average at each vertex.

Table 6 summarizes the keyboard shortcuts that can be used when extracting features.

Action	Keyboard Shortcut
Switch between Move a Point and Add a Surface	Tab
Surface Merging	Ctrl + U
Edge Merging	Ctrl + E

Table 6: Shortcuts for feature extraction tools

## 9.2 Attributes

Attributes may be applied to each feature. To apply an attribute to a feature, the user needs to first select that feature and enter corresponding information. New fields can also be created to suit the user's requirements. Moreover, an XML file can be provided containing a user's desired attribute list. The information in this XML file will be loaded automatically. To specify the XML file, please select "Feature Attribute File" in "General Settings" which can be accessed from the "File" menu.

## 9.3 Real-time True Orthorectification

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A true ortho can be created for a small region in real-time around a selected feature. To allow for true orthorectification, the necessary inputs need to be specified when entering feature extraction mode. The user then proceeds to the feature extraction process. At any time, the user can enable true ortho generation by toggling the "Display real-time true ortho" button. Note, as the user continues editing the selected feature, the true ortho will be automatically updated to reflect the changes. This enables the user to iteratively refine the polygon for the selected feature until the true ortho is a perfect fit.

# 10

## DISTRIBUTED PROCESSING

Correlator3D™ can benefit from the computers available on a local network to increase its processing power by multiple folds. The software can dynamically distribute processing tasks and manage communication with other stations with the software installed. It can also automatically handle situations in which a station goes suddenly offline during processing, or another becomes available, without the user having to intervene.

While the integration of these capabilities to Correlator3D™ is seamless, some aspects need to be considered when installing and operating the software.

### 10.1 Installation

When installing the software, the wizard specifically asks to install a special service used to automatically detect other stations equipped with Correlator3D™ on the local network. Note that each station must have a valid software license (local or network) in order to perform processing.

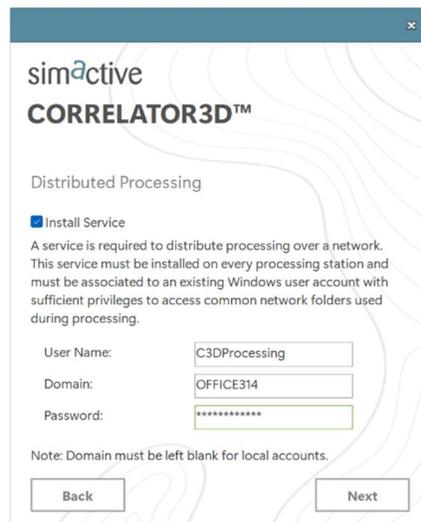


Figure 28: Service installation.

This service requires to be associated to a user with sufficient privileges to access common network folders used during processing (this user does not necessarily have to be the same on all stations). Note that even if another user is logged into the station, the service will still be associated to the user specified during the installation. This service will also be automatically started each time the computer is restarted.

While the installer will attempt to automatically add special rules to the Windows firewall, other firewalls may require to manually add them. Specifically, the following ports need to be accessible:

- C3DProc.exe: port 41831 (outbound), TCP and UDP
- C3DNetDiscovery.exe: 41832 (outbound), TCP and UDP

## 10.2 Settings

The settings related to the distributed processing can be found in the General Settings of the application ("File" menu). A critical aspect when enabling distributed processing is to make sure that the temporary folder of the main station is accessible to all processing stations. This is essential since this folder is where the remote stations will store the results of their tasks. If this folder is on a local disk of the main station, it first needs to be shared to the network. Then, it must be specified using the corresponding network address (e.g. "\\COMPUTER123\SharedTemp\") in the general settings, even if this folder is local.

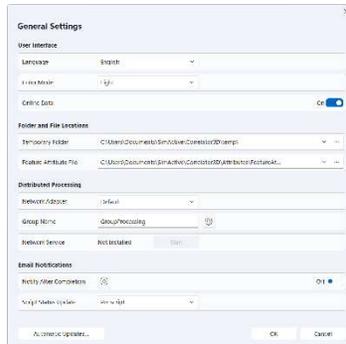


Figure 29: Distributed processing settings.

Other options can also be set such as the name of the processing group a station belongs to. Permissions can also be set to define which remote stations can access this station, or even to deny access to others.



At any given time, the Processing Station List window can be displayed using the corresponding button of the main toolbar. This window displays the processing stations that were automatically detected on the local network as well as their status. The most typical statuses are:

- **Available:** The station is available for processing.
- **Ready:** The station is locked by the main station, and ready to start processing.
- **Busy:** The station is currently being used by another station. It can also mean that the Correlator3D™ interface is opened on this station.

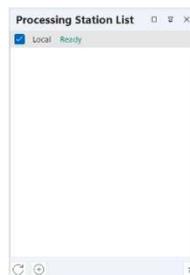


Figure 30: Processing station list.

In case of an error, the user can hover the cursor over a status to get further details. This window also allows to select, with the corresponding checkboxes, which station should be used for any oncoming process. Stations that were not automatically detected can also be added using the corresponding button.

## 10.3 Project Creation

---

Four processes can be distributed: aerial triangulation (tie point extraction), DSM generation, orthorectification, and 3D model generation (texture generation). When the user defines the parameters in the corresponding dialog, the processing station list will automatically be displayed in the project tree. The user can then verify which stations are currently ready for processing.

During processing, the user can assess the workload by monitoring in real-time the number of tasks that have been processed so far by each station. At any given time, it is possible to check or uncheck a station to dynamically adjust the computing power.

## 10.4 Processing

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Projects for which distributed processing is desired also need special attention at the time of creation. Input files (e.g. images) and project folder must be accessible to all processing stations. Again, if these files are on a local disk of the main station, they first need to be shared and added to the project using a network address.

## 10.5 Performance

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As photogrammetry projects usually consist of a considerable amount of data, extra care must be taken when choosing hardware. Specifically, the performance of the disk containing the images must allow fast access times as several stations will read and write data simultaneously. Consequently, the network must also support large bandwidth. Therefore, the following hardware is recommended to fully benefit from this capability:

- PCI Express NVMe Solid State Drives
- 10 Gigabit PCI Express network adapters
- 10 Gigabit network switch
- Cat6 Ethernet cables or better

# 11 TOOLS

## 11.1 Import EO Data

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Correlator3D™ features a tool to import EO data. The tool allows to load EO data stored in a file (ASCII format) and to arrange it according to the SimActive format. In the original file, the EO data must be ordered by columns and the tool assigns specific columns to particular EO values (i.e. image *name*, easting, northing, elevation, omega, phi and kappa). The interface also allows some rows or columns to be ignored.

The user must specify in which units the angular values are represented (degrees, radians or gradians) and the tool will convert them, if necessary, to degrees. An angular offset can also be added to kappa values by using the “Camera Mount Rotation” option. In addition, if values in the “ImageName” column do not include a file extension (e.g. tif, jpg or bmp), then the tool can automatically add one using the “Add Extension to Image Name” option.

The user must select a position and orientation system. The software operates using the "Easting/Northing" position and the "Omega/Phi/Kappa" orientation systems. However, a "Lat/Long" position and/or "Roll/Pitch/Yaw" orientation system may be specified. The tool will then perform the necessary conversion. Note, the user must specify a projection to allow conversion between different position and orientation systems. The orientation system can also be set to "Automatic". This will set omega and phi angle values to zero, and the kappa will be derived from the image positions.

Note, that the interface also allows the user to edit a particular cell value and to remove undesired lines.

To create an EO file, the user should perform the following operations:

1. Specify an ASCII file by pressing the corresponding "..." button.
2. Specify the delimiter(s) to be used by the software to recognize the columns in which EO data are represented.
3. Specify the input angular units.
4. If required, specify a camera mount rotation to add an angular offset to the kappa values.
5. If required, specify an extension to be added to image names.
6. Select the appropriate position and orientation system.
7. Select the altitude units.
8. If required, specify an altitude offset.
9. Assign EO data values to the appropriate columns by pressing on the buttons located at the top of the displayed ASCII file.
10. Remove any undesired rows by clicking on the corresponding check box located at the beginning of a line.

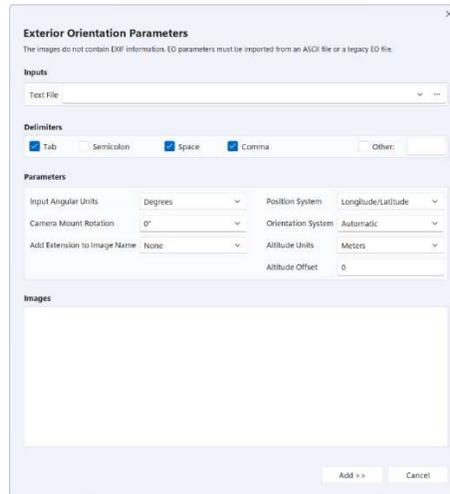


Figure 31: EO file creation dialog.

## 11.2 Import LIDAR LAS

Correlator3D™ can import LIDAR LAS files. If the “Extract DEM” option is selected, the software will automatically determine the sampling of the point cloud and create a regular grid, i.e. a DEM. The resulting DEM can then be used to extract tie points (as a reference DEM), tag GCPs, orthorectify images, etc.

Similarly, if the LAS files contain intensity information and the “Extract Image” option is selected, the software will create a reference ortho that will be added to the project tree. The reference ortho can then be used to extract tie points (as a reference ortho), tag GCPs, and assess the quality of the project.

To import LIDAR LAS files, the user should perform the following operations:

1. Select “Import” -> “LIDAR LAS File...” from the “File” menu.
2. Specify the files to be imported by clicking on the “Add Files...” button.
3. Select “Extract DEM” if a DEM is required.
4. Select “Extract Image” if a reference ortho is required. Specify the folder and the name of the resulting ortho.
5. Click on the “Process” button.
6. Save the generated DEM by selecting “Save DEM As...” using the contextual button in the project tree.

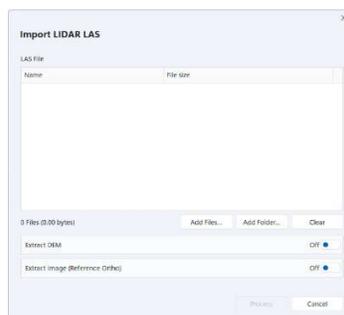


Figure 32: Import LIDAR LAS dialog.

## 11.3 Seed DEM Creation

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Correlator3D™ offers a tool to automatically create a seed DEM. The software creates a DEM with the boundaries computed from the provided project and with every elevation point set at the specified terrain height.

To create a seed DEM, the user should perform the following operations:

1. Select “Seed DEM Creation...” in the “Processes” menu.
2. Specify the average terrain height.
3. Click on the “Process” button. Real-time feedback on the overall progress of processing will be provided. Once the process is done, the seed DEM will appear in the main window.

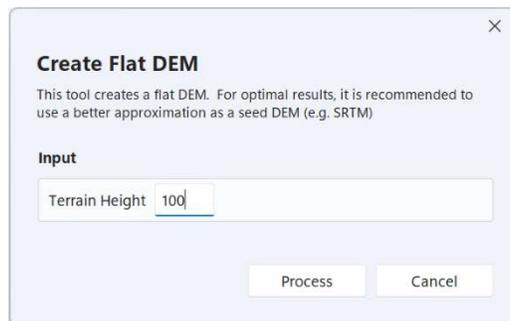


Figure 33: Seem DEM creation dialog.

## 11.4 Fiducial Detection

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Correlator3D™ features a tool for automatically detecting fiducials. The tool is useful for extracting the position of marks (in pixels), which are necessary for using any processing module of the software with scanned films. The fiducial detection tool is shown to the user when creating a project with scanned films.

Correlator3D™ supports fiducial marks that consist of two lines intersected in a perpendicular manner. These two lines can be continuous or not and the corresponding cross mark can be oriented in any way. Also, note that fiducials are assumed to be bright on a black background.

Fiducial detection is performed in four steps:

1. The user enters the required information in the fiducial detection dialog.
2. The user manually selects the fiducial marks for the first image.
3. Correlator3D™ automatically detects the fiducial marks for the remaining images.
4. Correlator3D™ automatically validates the detection results and prompts the user to manually select the fiducial marks for faulty images.

Detection results can be verified visually using images that the software automatically generates (these can be found in the temporary folder as described in Section 15.3). The figure below shows an example of a successful fiducial detection. Note that the center of the green mark represents the location where the software located a fiducial mark.

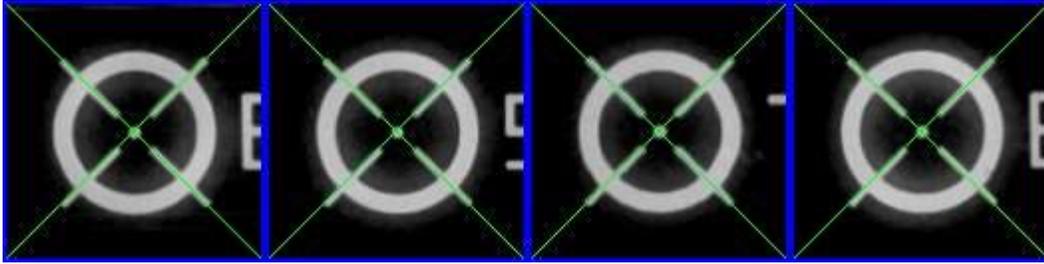


Figure 34: Sample fiducial detection results.

Fiducial marks that are incorrectly detected can be easily identified by looking at these images. The following figure presents such a situation. In that case, the user should manually correct the resulting exterior orientation file. Note that a warning will be reported in the log file (Section 15.1) when there was an error in the detection process.

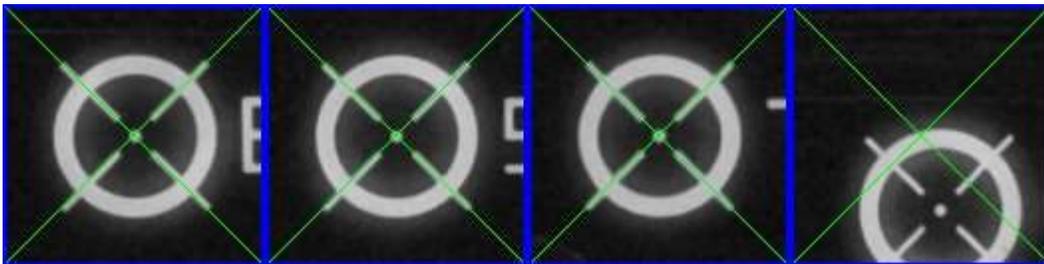


Figure 35: Sample fiducial detection results with one mark incorrectly identified.



*The user can skip the automatic detection phase and manually select the fiducial marks.*

To use the fiducial detection tool, the user should perform the following operations:

1. Drag each of the four images until a fiducial mark appears in the center of each frame under the green marks.
2. Turn on the "Skip automatic detection" if all fiducial marks need to be selected manually.
3. Click on the "OK" button when all fiducial marks are correctly selected.
4. Automatic detection is performed and real-time feedback on the overall progress of processing is provided.
5. Automatic detection of faulty images is performed. If necessary (or if the "Skip automatic detection" was turned on), the fiducial detection dialog for manual selection appears and these steps must be performed:
  - a. Drag the faulty fiducial marks under the corresponding green marks.
  - b. Click the "Next" button.
  - c. Repeat steps a) and b) until process is completed.

When using the fiducial detection dialog for manual selection, the size of the fiducial marks can be adjusted by using the "+", "-", and "1:1" buttons. The fiducial marks are selected by dragging their image portion over the intersection of green lines, either by using the mouse or the arrow keys on the keyboard. If the arrow keys are used, "Shift" and "Ctrl" keys can serve for coarser, but faster positioning, while the arrow keys alone are better suited for fine-tuning purposes.

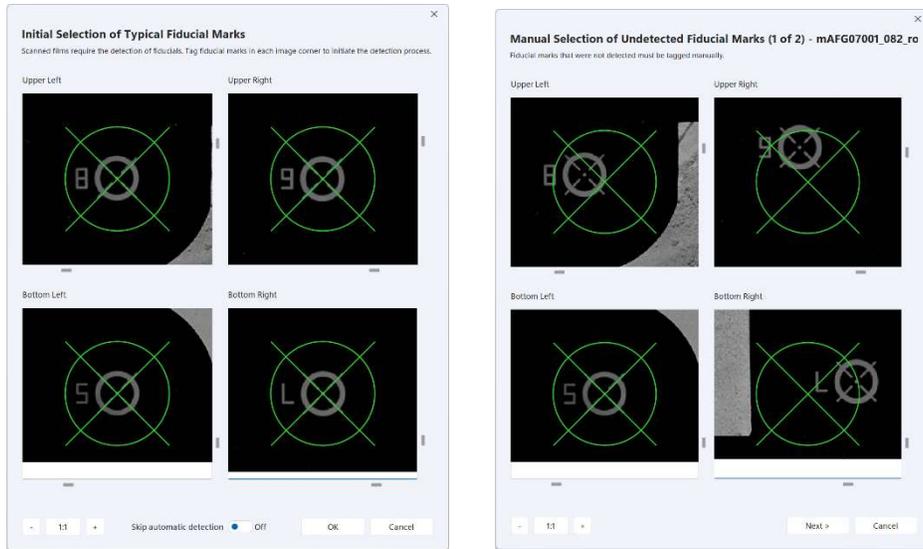


Figure 36: Fiducial detection dialogs for manual selection. On the left, all fiducial marks were correctly selected. On the right, a faulty detection must be corrected.

## 11.5 Calibrated Reflectance Panel Creation

For multispectral camera projects, the user might require to use calibrated reflectance panels to calculate reflectance information for each image. These panels are used to compensate for the lighting conditions at the time of each survey, allowing comparison over different days or at different times of the day. Images of the panels are usually taken before and after each flight to provide an accurate representation of the amount of light reaching the ground at the time of capture.

Calibrated reflectance panels must be added before orthorectifying the images since the reflectance information is calculated at this time. Panels are added to a project on a per-image basis. In other words, a same panel can be taken in several images over time and by several cameras, and will consequently need to be added several times to the project. For each panel, the calibrated reflectance (or albedo) values must be known for each wavelength. These values are usually provided by the panel manufacturer.



*If more than one panel image is captured (for example at the beginning and end of a flight) or if data are captured in multiple flights, and a calibration panel image is taken at the beginning of each flight, the software will extend the analysis by interpolating across time.*

To add a calibrated reflectance panel, the user must hover the cursor over the camera used to capture the image, under the Reflectance Panel portion of the project tree, and press the “Add a panel” contextual button.

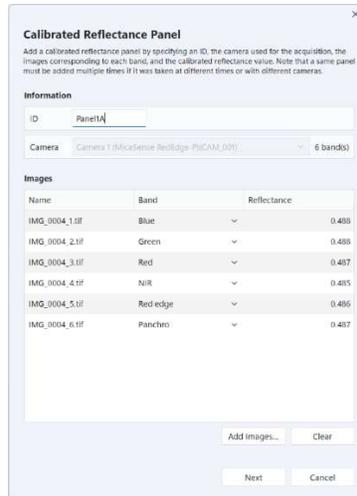


Figure 37: Calibrated reflectance panel dialog.

The following operations must then be performed:

1. Specify an ID for the panel. It could consist of the ID of the panel, and the time at which it was captured.
2. Select the camera that was used to capture the panel.
3. Click on the "Add Images" button to select the corresponding image. If images generated by the camera has one file per band, then select the corresponding files. The total number of images should be at most the total number of bands of the camera.
4. For each band, specify the calibrated reflectance (or albedo) value.
5. Click on the "Next" button.
6. Click on the center of the panel to indicate its location. The software will then start automatic detection of the panel in each image/band.
7. Visually inspect the boundaries of the rectangle to make sure it matches the panel and drag the corners if it is required.
8. Click on the "Next" button and adjust the boundaries in all other images/bands.



*Some calibration panels include a QR code that are automatically recognized by Correlator3D™. Consequently, the dialog are pre-filled with the calibrated reflectance values, and the boundaries of the targets are already selected.*

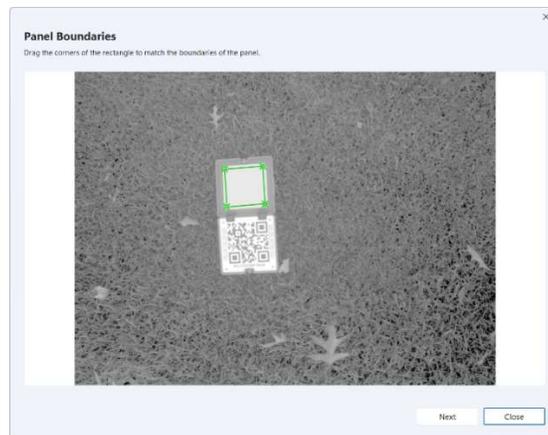


Figure 38: Panel boundaries dialog.

## 11.6 GCP Creation

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Correlator3D™ features a tool to create GCPs for UAV/medium/large format and satellite sensors. The GCPs are used during the aerial triangulation process. The tool enables the user to specify pixel coordinates of ground control points in a visual environment. GCPs may be created by specifying their positional coordinates. The software uses these inputs to automatically determine which images contain the specified GCP. These images are then displayed in the visual interface and the user is requested to pinpoint the locations of ground control points.



*The GCP creation tool is only available in the AT module.*

### 11.6.1 Creating and Importing GCPs

There are three methods for creating GCPs. The first method is by using the project tree where the user must hover the cursor over the GCP portion, and press the “Add a new point” contextual button. The GCP editing dialog will then be displayed to manually specify the coordinates of the GCP.



The second method is by directly clicking on a specific location in the main window using the “Create a GCP” tool from the aerial triangulation toolbar. It will automatically trigger the GCP Editing dialog, with all the coordinates of the GCP already filled. If a DEM, a point cloud or a 3D model are simultaneously loaded in the project, the software will first ask for what elevation to be used for the GCP.

Finally, when GCPs are already specified in a text file (in ASCII format), they can be imported in the aerial triangulation module. The file should be organized in columns such that the tool can assign a specific column to a GCP field (i.e. GCP ID, X, Y, and Z). The interface also allows ignoring some rows or columns. Imported GCPs are then displayed in the project tree where they must be selected for editing in order to add observation data.

The following operations must be performed to import a GCP file:



1. In aerial triangulation mode, select “Import GCP File...” in the “Processes” menu.
2. Specify an ASCII file by pressing the corresponding “...” button.
3. Specify the delimiter(s) to be used by the software to recognize the columns in which GCP data are represented.
4. Specify the projection system of the coordinates to be imported.
5. Choose if the new GCPs should be added to the existing ones or should replace them.
6. Assign GCP data values to the appropriate columns by pressing on the buttons located at the top of the displayed ASCII file.
7. Remove any undesired rows by clicking on the corresponding check box located at the beginning of a line.
8. Click on the “Import” button.
9. Add observation data to each GCP by editing them using the corresponding button in the project tree.

## 11.6.2 GCP Editing Dialog

The GCP Editing dialog is used to edit GCP properties, such as its ID, description and coordinates, and to tag it in the images. The dialog is divided into four sections:

- Information: this section is located at the top of the window and contains the GCP properties. For convenience, it can be collapsed using the blue triangle button in the upper-right corner.
- Observations: this section occupies the largest part of the window. This is where the user can adjust the location of the GCP in the images.
- Ribbon: this section is located under the observation section. It contains an overview of all the observations of the GCP along with other images in which the GCP is likely to be found.
- Zoom and Navigation: this section can be found at the bottom of the dialog. It contains controls to help navigate the images.

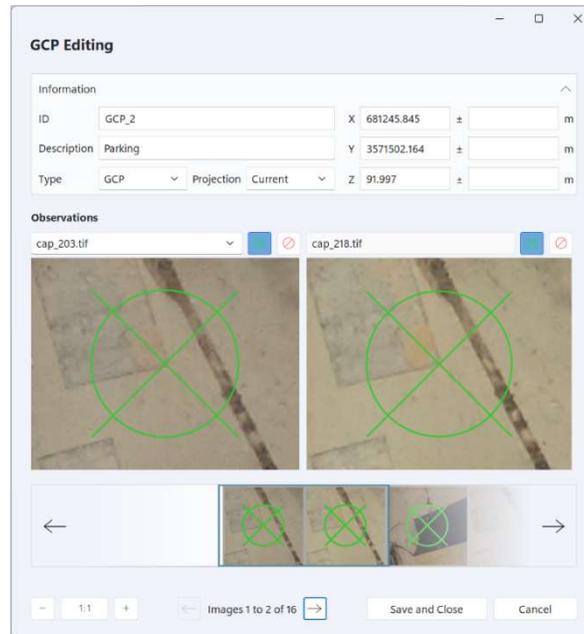


Figure 39: GCP Editing window.

There are four (4) GCP types which are "GCP", "GCP\_XY", "GCP\_Z" and "check point". The first three types are used to distinguish between varying forms of positional certainty. For example, the user may need to specify a GCP for which they are only certain about the Z component. In this case, GCP type "GCP\_Z" will be used. Note, the user will still have to specify an approximate X and Y component. The effect of this is that the software will now treat this GCP accordingly in the aerial triangulation process, placing a high importance on the Z component, while allowing room for error in the X and Y components. Check points are GCPs that are not taken into consideration when performing bundle adjustment. They are generally used for quality assessment.

GCP TYPE	Certain	Uncertain
GCP	XYZ	None
GCP_XY	XY	Z
GCP_Z	Z	XY

Table 7: GCP type description.

The user has the option to add uncertainty information. As described in in section 7.1.5, when the uncertainty values are left blank, the general uncertainty values will be applied during bundle adjustment. If an uncertainty value is specified in the GCP Editing dialog, it will overwrite the general uncertainty values for this specific point. This way, the user can specify a global uncertainty for all points and redefine it on a point-by-point basis. If uncertainty is used, it must be specified for all three coordinates (X, Y, and Z).

Once coordinates are specified, Correlator3D™ will project the point in each image and populate the ribbon with the images that most likely contain the GCP. The software uses knowledge on already identified GCPs and current IEO parameters to select the best image candidates. Consequently, each time a new GCP is added to the project, Correlator3D™ becomes better at selecting candidate images.

The observation section of the dialog will display up to three images depending on the window size. These are used to adjust the GCP location in each image. Initially, an image candidate has an “unspecified” state. This state indicates that the user has not yet validated nor discarded the image. To validate an image, the user must adjust the GCP location in that image by clicking and dragging the image until the green aim is on top the GCP.



If the GCP is already at the proper location, the image can be validated by pressing the green aim button on the top-right corner of the image.



An image can also be discarded by checking the red discard button next to the green aim button.

Unchecking both the aim button and the discard button will revert the image back to the unspecified state. Images in the disabled or unspecified state will not be used during bundle adjustment as there is no functional difference between both. The disabled state exists to let the user differentiate images that have been rejected from those that require attention.

The ribbon is used to navigate around the image candidates. The blue rectangle indicates which images are currently displayed in the observation section of the window. To change the images being edited, the user can drag and drop the ribbon at the proper location. An alternate option is to use the arrows on the left and right side of the ribbon or those under the ribbon.



When the ribbon is dragged completely to the left (therefore showing the rightmost part of the ribbon) a special “+” button is visible. Clicking this button will add new image candidates to the ribbon.

At any time, the user can jump to a specific image by selecting it in the combo-box located above the left image in the observation section of the dialog. If necessary, the image will be added to the ribbon.

Each time the location of the GCP is adjusted in an image, the software recalculates the estimated location of the GCP in the images marked as “unspecified”. The ribbon is updated in real time to reflect these adjustments. This means that each new observation for the GCP improves the estimated location of the GCP in the other images.



*Scrolling the ribbon is a fast and easy way to identify and validate the GCP observations.*

The zoom options located in the lower-left of the window are used to adjust the zoom factor applied to the images displayed in the observation portion of the dialog. Cancel and save buttons are located

in the lower-right of the window. Clicking “Save and Close” will update the GCP. Clicking “Cancel” will discard the changes and close the window.

To edit a GCP, the user should perform the following operations:

1. Fill the required ID (name), type, projection and XYZ coordinates properties. If required, add a description and an uncertainty.
2. Mark which images are to be used with the GCP.
  - a. Use the ribbon to navigate between the images. Use the “+” button to add images if necessary.
  - b. Adjust each image to tag the exact GCP location. Use the zoom options to help find the exact location of the GCP.
3. After all the observations have been added click the “Save and Close” button to update the GCP file.

## 11.7 DEM Merging Tool

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Correlator3D™ DEM merging tool allows combining DSM or DTM results that were created separately. It is useful to process a project in multiple parts (e.g. at different times or in parallel on multiple machines) and merge different tiles of DEMs together afterward. It can also help to recover intermediate results from individual pairs when, for some reason, the DSM process is interrupted. Correlator3D™ implements an intelligent data fusion approach that leads to consistent data sets, even when there are minor discrepancies along adjacent tile boundaries.

The DEM merging tool can be accessed from the Tools menu and does not require any DEM to be loaded in the main window. It can merge files stored in different formats and horizontal resolutions. Note that when merging DEM sets having different horizontal resolutions, the resulting data will automatically inherit the finest resolution. Also, if there is no overlap between adjacent data sets, Correlator3D™ will set the corresponding elevation values as undefined. An option to fill gaps in the resulting DEM is also available. This option allows the user to get a DEM in which small areas where elevation values were left undefined are filled with interpolated terrain data. The final merged data will be displayed in the main window and can then be saved by the user.

To merge DEMs, the user should perform the following operations:

1. Select “DEM Merging...” in the “Tools” menu.
2. Specify the files to be merged by clicking on the “Add Files...” button. A file browser will appear. Select the files to be added and click “Open”. The list will then be updated. Note that all files can be removed from the list (e.g. in case of an error) by pressing on the “Clear List” button.
3. Click on the “Merge” button. Real-time feedback will be provided on the overall progress of processing. Once the process is done, the resulting DEM will appear in the main window.
4. Save the merged DEM by selecting “Save DEM As...” in the “File” menu.

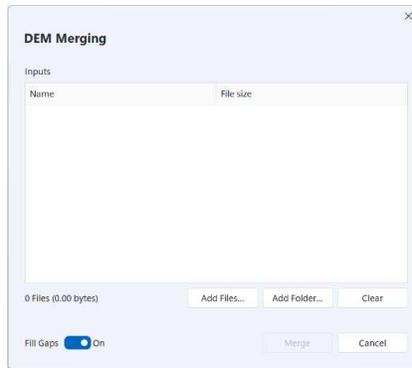


Figure 40: DEM merging dialog.

## 11.8 Export EO and Camera Parameters

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Correlator3D™ can export the EO information and camera parameters. In order to perform this, the user must specify a folder in which the information is saved. In the case of a frame-based project, one EO file and one calibration file per camera will be created. For satellite projects, one RPC file will be produced for each image. These files will be exported as simple text files, which can be used later on in the software.

## 11.9 Export Mosaic

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Users can export the final mosaic using a tile definition file and selecting the type of mosaic they want to create. Standard mosaics, index maps, and reflectance maps can be created. Users can export only a portion of the mosaic using the "Crop Area" option, as defined by a polygon stored in a DGN file or a Shapefile.

Users can either specify a fixed size for the tiles, individual tile size and coordinates through a tile definition file or ask for a single tile. If a fixed tile size is specified in the dialog, each tile will have that size, except for tiles located on the border of the mosaic. In such cases, the size of the tile is simply reduced to remove unnecessary undefined areas. The tiles are created to be juxtaposed one after the other with no overlap between two adjacent tiles. The naming of the tiles describes the spatial relation between each other. The name convention is as follows: Name\_LineNumber\_ColumnNumber.tif.



*The position and orientation of the input orthorectified images can lead to situations where some tiles only contain undefined data (completely black areas). When specifying a fixed tile size in the Export Mosaic dialog, if such a situation occurs, the corresponding tiles are not created by Correlator3D™. This behavior is part of an optimization effort to reduce memory and disk requirements while improving overall performance.*

If a tile definition file is used, then the tile size specified will be respected, even if the resulting area contains unnecessary undefined areas. Moreover, each tile will be created even if they do not contain any data at all.

To export a mosaic, the following steps must be performed:

1. Specify the Mosaic Type. Click on the corresponding settings button to specify the band ordering or the index type if required .
2. Specify the Mosaic Folder that will contain the mosaic using the corresponding drop-down menu.
3. Specify the file format of the mosaic.
4. If a Crop Area is used, specify the constraint.
5. Specify the Tile Definition File if required.
6. If no Tile Definition File is used:
  - a. Specify the name for the mosaic.
  - b. Specify the tile size or the Single Tile option.
7. Click on the “Process” button. The mosaic will then be exported using the parameters specified.

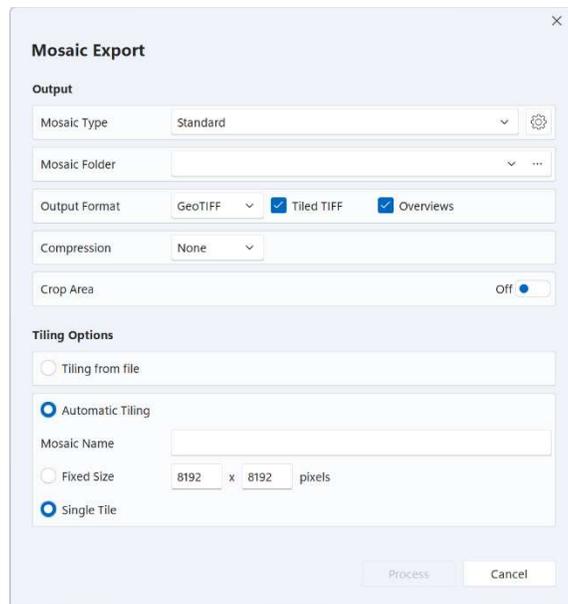


Figure 41: Export mosaic dialog.

### 11.9.1 Index Map

A mosaic can be converted and exported to an index map. Users can choose from a list of predefined indices including:

- NDVI
- BNDVI
- GNDVI
- LCI
- NDRE
- SIPI
- SIPI2
- ARVI
- GCL
- NBR

Custom indices can also be specified through a formula. This formula supports different operations between the imagery bands, including addition, subtraction, multiplication and division. The resulting index can be outputted either as a floating point value or following a color map. This color map is defined by the number of classes (colors), as well as the bounds of the index.



*If reflectance information is available, it will be used to calculate indices, thus providing even more accurate maps. Reflectance information is only available for multispectral projects for which the sun sensor or calibrated reflectance panels were used during orthorectification.*

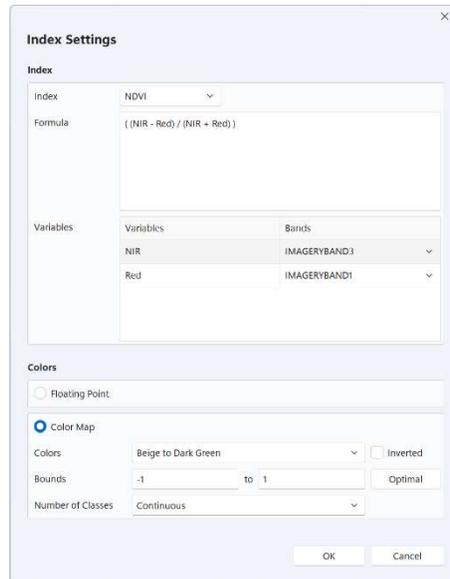


Figure 42: Index settings dialog.

## 11.9.2 Reflectance Map

If reflectance information is available, a mosaic can be exported to a calibrated reflectance map. Reflectance information is only available for multispectral projects for which the sun sensor or calibrated reflectance panels were used during orthorectification.

The resulting reflectance map will be outputted as 32-bit floating point values ranging between 0 and 1, with undefined pixels set to -1. The map will contain as many bands as the input imagery. If an infrared band is available, it will also be outputted in the same file as 32-bit floating point values, corresponding to the temperature in Kelvin.



*If a mosaic containing reflectance information is exported with the "Standard" option, reflectance values of each band will be stretched independently between 0 and  $2^N-1$ , where N corresponds to the number of bits of the input imagery.*

## 11.10 Export DEM

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### 11.10.1 Export DEM Tiles

Correlator3D™ can divide a DEM in multiple tiles. The user can either specify a fixed size for the tiles or specify individual tile sizes and coordinates through a tile definition file. If a fixed tile size is specified in the dialog, each tile will have that size, except for tiles located on the border of the DEM. In such cases, the size of the tile is simply reduced to remove unnecessary undefined areas. The tiles are created to be juxtaposed one after the other with no overlap between two adjacent tiles. The naming of the tiles describes the spatial relation between each other. The name convention is as follows: Name\_LineNumber\_ColumnNumber.tif.



*The shape of the input DEM can lead to situations where some tiles only contain undefined data (completely black areas). If such a situation occurs when specifying a fixed tile size in the Export DEM Tiles dialog, the corresponding tiles are not created by Correlator3D™. This behavior is part of an optimization effort to reduce memory and disk requirements while improving overall performance.*

If a tile definition file is used, the tile size specified will be respected, even if the resulting area contains unnecessary undefined areas. Moreover, each tile will be created even if they do not contain any data at all.

The format of the output DEM tiles can be specified in the dialog. If a definition file is used, the format is specified through the extension of the DEM tiles.

The tool can be accessed from the File menu and requires a DEM to be loaded from the project tree.

To export DEM tiles, the following operations should be performed:

1. Select a DEM from the project tree. The DEM will be displayed in the main window.
2. Select “Export” -> “DEM” -> “DEM Tiles...” in the “File” menu.
3. If a tile definition file is used
  - a. Select “Tile Definition”.
  - b. Specify the tile definition file by pressing on the corresponding “...” button. .
4. Specify the folder that will contain the tiles by pressing on the corresponding “...” button.
5. If no tile definition file is used
  - a. Specify the name for the mosaic.
  - b. Specify the tile size.
6. Specify the format for the DEM tiles.
7. Click on the “Process” button. Real-time feedback will be provided on the overall progress of processing.

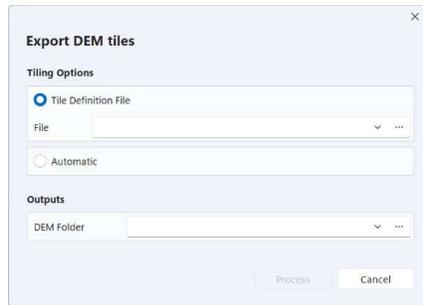


Figure 43: Export DEM tiles dialog.

### 11.10.2 Export LIDAR LAS and ESRI Shapefile

Correlator3D™ can export a DEM into a LIDAR LAS file or an ESRI Shapefile. Using these formats, elevation grids will be exported as a series of 3D points. The tools can be accessed from the File menu and requires a DEM to be loaded in the main window.

To export a DEM into the LIDAR LAS or ESRI Shapefile format, the user should perform the following operations:

1. Select a DEM from the project tree. The DEM will be displayed in the main window.
2. Select “Export” -> “DEM” -> “LIDAR LAS File...” or “ESRI Shapefile” in the “File” menu.
3. Specify the name and the location of the file to be exported.

### 11.10.3 Export with Geoid

Correlator3D™ can export a DEM on which a geoid will be applied. The geoid file must be provided in the GTX file format.

The tool can be accessed from the File menu and requires a DEM to be loaded in the main window.

To export a DEM with a geoid, the user should perform the following operations:

1. Select a DEM from the project tree. The DEM will be displayed in the main window.
2. Select “Export” -> “DEM” -> “With Geoid...” in the “File” menu.
3. Specify the geoid file by pressing on the corresponding “...” button.
4. Specify the output DEM by pressing on the corresponding “...” button.
5. Click on the “Process” button. Real-time feedback will be provided on the overall progress of processing.



Figure 44: Export with geoid dialog.

## 11.11 DEM Inspection

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Correlator3D™ DEM inspection tool is used to generate statistics about the quality of a DEM against reference data, i.e. elevation points provided in a ShapeFile or a SimActive GCP file. The software automatically computes the differences in elevation and provides statistics including bias error, standard deviation, RMS error and maximum error.



*Statistics are displayed in a window at the end of the process. They can be saved as a text file.*

To export DEM tiles, the following operations should be performed:

1. Select “DEM Inspection...” in the “Tools” menu.
2. Specify the DEM to be inspected using the corresponding drop-down menu.
3. Specify the reference data using the corresponding drop-down menu.
4. Click on the “Process” button. Real-time feedback will be provided on the overall progress of processing.



Figure 45: DEM inspection dialog.

## 11.12 Change Detection

---

Traditionally, change detection is performed by comparing two images. This approach is not robust in general since only changes in the appearance of the scene are detected and such changes do not necessarily imply structural changes. Correlator3D™ allows change detection by comparing DEMs instead of images. Such a comparison is possible since the software can quickly and automatically process 3D data.

Correlator3D™ requires two DEMs, which should be generated from two different image sets of the same area. It performs a comparative analysis and determines in 3D the importance of changes. The software outputs change detection results as a DEM with values corresponding to the differences in elevation between the two DEMs. The results can be optionally outputted as color information superimposed on a mosaic of orthophotos. This mosaic gets converted to grayscale and structural changes are highlighted using a specific color scheme: negative elevation changes (e.g. objects that have disappeared) are displayed in tones of yellow to red according to their importance (small to large changes respectively) while positive elevation changes (e.g. new objects) are shown in tones of dark to light blue (small to large changes respectively). A detection range in meters is used and only changes that are within the specified range (vertically) will appear.

To perform change detection, please follow these steps:

1. Select “Change detection...” in the “Tools” menu.
2. Specify the reference DEM (i.e. the DEM as it appears before changes) using the corresponding drop-down menu.
3. Specify the comparison DEM (i.e. the DEM as it appears after changes) using the corresponding drop-down menu.
4. If a change detection mosaic is required:
  - a. Turn on “Display Changes on Mosaic”.
  - b. Specify the “Input Mosaic File” of the input mosaic using the corresponding drop-down menu. This file can be either a mosaic definition file or a tile definition file. Change detection results will be overlaid on the mosaic after the processing is completed. This mosaic can correspond either to the images taken before or after the changes.
  - c. Specify the folder where the change detection mosaic will be generated using the corresponding drop-down menu.



*If new 3D structures are mostly expected, then the mosaic corresponding to the image data taken after changes should be used. If it is anticipated that structures have in general disappeared, then the input mosaic should consist of the image data collected before changes have occurred.*

5. Specify the detection range. This implies that only changes within that range (vertically) will be detected.
6. Click on the “Process” button. Real-time feedback will be provided on the overall progress of processing. Once the process is done, the change detection DEM will appear in the main window.
7. Save the DEM by “Save DEM As...” in the “File” menu.



Figure 46: Change detection dialog.

## 11.13 Point Cloud Filtering

The Correlator3D™ point cloud filtering tool enables users to filter a point cloud based on the number of observations assigned to each point during point cloud generation (an optional product of the DSM generation process). The tool contains a list of numbers, which correspond to each possible number of observations. For each number, there is a checkbox that users can uncheck if

they do not want to keep points in that category. Real-time visual feedback is provided to help users make informed decisions about which categories to keep. Once users have made their selections, they can click on the "Process" button, and the software will remove any unchecked categories from the point cloud. This allows users to focus on specific areas of interest within the point cloud with greater precision and accuracy, by eliminating points that do not meet their desired criteria.

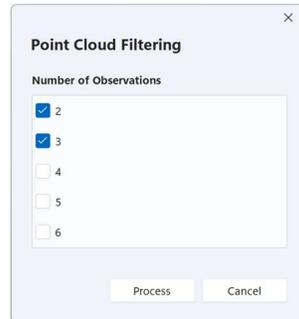


Figure 47: Point cloud filtering dialog.

## 11.14 Point Cloud Colorization

---

The Correlator3D™ point cloud colorization tool is used to colorize a point cloud using a mosaic. The software automatically determines correspondence between 3D points and pixels.



*When colorizing a point cloud, it is strongly recommended to use an appropriate mosaic. As an example, if a point cloud was generated for a dense urban area, then the mosaic should be generated using true orthos, i.e. orthos generated on a DSM. Otherwise, discrepancies could be observed between points and colors.*

To perform point cloud colorization, the user must follow the listed steps:

1. Select the point cloud to be colorized from the project tree.
2. Select "Point Cloud Colorization" in the "Tools" menu.
3. Save the modified point cloud by selecting "Save point cloud As..." using the contextual button in the project tree. Note that if the point cloud is saved under a different name than its corresponding DEM, it will be excluded from the project tree.

## 11.15 DEM Contour Extraction

---

The Correlator3D™ DEM contour extraction tool is used to generate equally spaced contour lines from the currently loaded DEM and save them in a vector file. The contour lines are extracted based on two parameters: the interval, which corresponds to the elevation interval between contour lines, and the offset, which corresponds to the offset from zero relative to which to interpret intervals.

To perform DEM contour extraction, the user can follow the listed steps:

1. Select the DEM you wish to use for contour extraction from the project tree.
2. Select "DEM Contour Extraction..." in the "Tools" menu.

3. Specify the contour interval and offset.
4. If a specific elevation attribute is required in the vector file, turn on the “Elevation Attribute” option, and specify the name of the attribute.
5. Click on the “Process” button. Real-time feedback will be provided on the overall progress of processing.
6. Save the generated contour by selecting “Save contour” using the contextual button in the project tree.

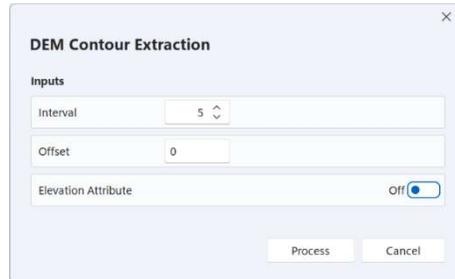


Figure 48: DEM contour extraction.

# 12

## RESULTS SHARING

Once a project has been generated, the user can upload the results in the cloud. Correlator3D™ will then produce a secure link to an online data viewer that can be shared with customers or other users. This functionality is provided through Cesium, an end-to-end platform for tiling, visualizing, and analyzing 3D geospatial data on any device, including tablets and smartphones.



*Sharing the resulting link does not compromise the security of the Cesium account. This link will give access to the corresponding data only.*

To enable sharing, the following steps must be performed:

1. Subscribe to Cesium.
2. Setup a Cesium account.
3. Link Correlator3D™ to a Cesium account.

### 12.1 Cesium Subscription

---

To subscribe to Cesium. The following steps must be performed:

1. Select a data plan by visiting: <https://cesium.com/pricing/>
2. Create an account following the instructions from Cesium.

### 12.2 Cesium Setup

---

Two new access tokens must be created using the Cesium web interface. The first token (C3D\_Upload) will be used by Correlator3D to upload project data directly to the Cesium account. The second token (C3D\_Share) will be used by Correlator3D to generate hyperlinks that can be shared with customers. The following steps must be performed:

To subscribe to Cesium. The following steps must be performed:

1. Login to your Cesium account (<https://cesium.com/ion/signin/>) using a web browser.
2. Click on the “Access Tokens” tab.
3. Click on the “Create token” button.
4. Specify a name for the first token used for uploading (e.g. C3D\_Upload).
5. In the “Scope” section, turn on all the options.
6. In the “Resources” section, select “All assets”.
7. Click on the “Create” button.
8. Specify a name for the second token used for sharing (e.g. C3D\_Share).
9. In the “Scope” section, turn on the “assets:read” option only.
10. In the “Resources” section, select “All assets”.
11. Click on the “Create” button.

## 12.3 Correlator3D™ Setup

---

To link Correlator3D to a Cesium account, the following steps must be performed:

1. In Correlator3D, in the “Share Results” dialog, select “Add...” from the drop-down menu in the “Cesium Profile” section.
2. Specify a name and a description for your profile. This profile will contain the two required Cesium access tokens for uploading and sharing.
3. In your Cesium account webpage, click on the “Access Tokens” tab.
4. Select the “C3D\_Upload” access token and copy the token string using the corresponding “Copy to clipboard” button.
5. In Correlator3D, paste the token string in the “Upload” text box, in the “Cesium Access Tokens” section.
6. Repeat steps 4 and 5, but this time for the “C3D\_Share” token. Paste the string in the “Share” text box.
7. Click on the “Ok” button.

**Add Cesium Profile**  
Add a Cesium profile to Correlator3D by specifying its access tokens.

**Information**

Name	ProfileXYZ
Description	Tradeshaw

**Cesium Access Tokens**

Upload	kj51342kj51342kj513knt4Inglkrjehetgld4jhtlkgj4hkjn54tkjnlkjb4k4jnk3456jh6k4j3h5kj34hk534nkr4jnkj43n5k34jn5k34jn5k43jnkj423jn4kj23nk4jnk23jn
Share	hjlkjashkfhjnsdkjvnsdkavjnkndnk2nj5k2j34n5k4j32n43k2j4n3k2jn4k32jn4k32432342lkjfdlkjfdlrkj5432kj432kj4l32kj4l32kj4l23kjelk23jlkj5l2d

OK Cancel

Figure 49: Cesium profile window.

## 12.4 Sharing Results

---

To share results, the following steps must be performed:

1. With a project already loaded in Correlator3D, click on “Share Results...” in the “File” menu.
2. Select the Cesium profile to be used.
3. Specify a name for your project.
4. Specify the projection of the project if it was not previously specified during processing.
5. Select the products to be uploaded. Note that for DEMs, point clouds and 3D models, only the products that are active (selected) in the project tree will be uploaded.
6. Specify the band ordering of the imagery if required.

7. Click on the “Ok” button.
8. Once the project is uploaded to Cesium, a dialog with a shareable link to the online data will displayed. The same link can also be found in the log.



*Note that uploaded data can only be deleted using the Cesium account webpage. However, if a project with the same project name is uploaded, the corresponding data will be overwritten.*

A screenshot of a 'Share Results' dialog box. The dialog has a title bar with a close button (X) in the top right corner. Below the title, there is a subtitle: 'Upload the results of the current project to Cesium and produce a shareable link.' The dialog is divided into several sections: 'Cesium Profile' with a 'Name' dropdown menu set to 'ProfileXYZ' and a 'Description' text field; 'Project' with a 'Name' text field containing 'East Mine', a 'Projection' dropdown menu set to 'Unknown' with a gear icon, and a 'Products' section with four checkboxes: 'DEM' (unchecked), 'Mosaic' (checked), 'Point Cloud' (unchecked), and '3D Model' (unchecked); and 'Settings' with a 'Band Order' text field containing '(1, 2, 3)' and a gear icon. At the bottom left, there is a link to 'Cesium Quickstart Guide'. At the bottom right, there are two buttons: 'Process' and 'Cancel'.

Figure 50: Share results dialog.

# 13

## SCRIPTING MODE

Correlator3D™ includes a scripting mode for advanced users who desire to fully automate their processing tasks.

### 13.1 Script

---

A script simply consists of a plain text file containing a series of instructions that the software will execute sequentially. The syntax is very simple: each operation starts with the process name and all necessary input/output parameters are then specified. Here is an example for a DSM generation process:

```
<DSMGeneration>
{
    InputEO           C:\MyProject\IEO\Step_1\Step_1.iew
    Resolution        Optimal
    VertAccuracy      Precise
    OutputDEM         C:\MyProject\DEM\DSM.asc
}
```

Note that the order in which the process parameters are specified is not important. The user can perform as many operations as desired. Input files that do not exist can be specified as long as previous operations create them. For DSM generation and orthorectification, the optimal resolution or overlap can be set by entering “Optimal” (not case sensitive) in the corresponding field. Similarly, the user can set the maximal resolution by entering “Maximal” or “Coarse” in the corresponding field. A description of the format of script files is included in Section 0.

Once a script file is created, it can be run by selecting “Run Script...” in the “File” menu. Real-time feedback on the overall progress of processing is provided during execution.

Please refer to Appendix A for the script format description.

### 13.2 Command Prompt

---

Instead of using the GUI to interact with Correlator3D™, the user may wish to use a command prompt to run individual scripts and batch files quickly. Navigate to the Correlator3D folder and type “C3D” to display the possible options. For example, the following command:

```
C:\Program Files\SimActive\Correlator3D\C3D
```

will display the possible options on the command prompt screen provided the software was installed in that directory.

To run a script:

```
C:\Program Files\SimActive\Correlator3D\C3D PathToMyScript
```

The list of commands is summarized in Table 8:

Command	Action
/f	Specifies the filename and path of the SimActive script file. "/f" is optional.
/v	Verbose mode. Displays all the messages on the overall progress of processing.
/m	Messages only. Date and time information is not displayed.
/p	Show progress on stdout. Displays progress information on the standard output stream.
/s <names>   <IPs>	Processing station(s). Specifies the processing station(s) to be used for distributed processing.
/r	Redirect messages to file. Redirects messages from standard output to the specified file. Progress messages are not redirected.
/n none   perScript   perProcess	No email notification. Only notify at the end of the script. Notify after each process of the script.

Table 8: Command line operations summary.

# 14

## EMAIL NOTIFICATION

Users can be notified by email on the progress of processing. Depending on the operation being performed, the email notifications will include details about the inputs and the outputs. For aerial triangulation, the quality report will also be attached.

This option can be activated in the “General Settings” from the “File” menu. Email account parameters and the list of recipients can be set in the corresponding “Email Configuration” dialog. These parameters are specified by the email provider.

When executing a script, two types of status update are available: per script, and per process. If “per script” is selected, a notification will be sent only when the script is completed. If “per process” is selected, a notification will also be sent each time an operation is completed.



*While the default behavior is specified in the “General Settings” dialog, users can toggle the notifications directly in the progress bar during processing.*

# 15

## TROUBLESHOOTING

### 15.1 Log Window and Log File

---

Correlator3D™ includes detailed warning and error messages to facilitate troubleshooting. In addition, all major operations performed during processing are displayed in the log window. This window is fully dockable, allowing the user to customize their Correlator3D™ environment. Warning and error messages are color-coded in yellow and red respectively.

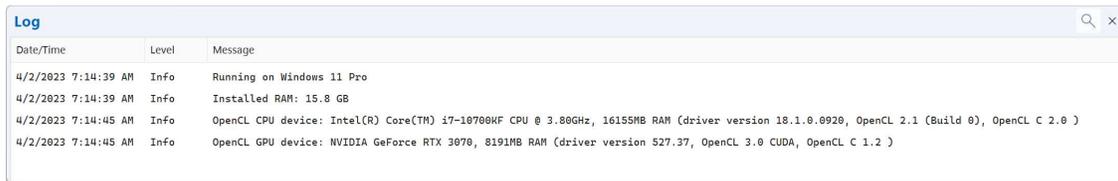


Figure 51: Log window.

The content of the log window is automatically saved in a log file. This can be particularly helpful if, for some reason, the processing is interrupted. The file is located in the folder "My Documents\SimActive\Correlator3D\Logs" and named "Correlator3D\_Log.xml". The file can also be accessed directly from the user interface by selecting "Log File" from the "Help" menu. A new log file is created each time the software is launched and logs information until the program is closed. Copies of the twenty most recent log files are automatically stored in the same folder.

### 15.2 Good Practice

---

As a first step, the user should perform a test on a few images before processing an entire project. This will ensure that there is no problem with the input data. It will also allow verifying that both the results and the required processing time meet expectations. Input parameters (depending on the module used) can be varied, and small scale tests can be repeated until satisfactory results are produced. Note that this recommendation does not hold for the aerial triangulation module, as it requires as much input data as possible.

### 15.3 Temporary Files

---

Different temporary files are created during data processing. In the case of the DSM generation process, each individual file, which is stored in the SimActive model format (.smf files), contains DSM generated from a given pair. Temporary files are named according to the first image of the pair processed. At the end of the DSM generation process, these individual files are automatically merged to produce a single DSM.

If the DSM generation process is interrupted in the middle of a large batch process, then these files can be retrieved and merged manually using the DEM merging tool. The user can change the location of the temporary folder by selecting “General Settings” from the “File” menu and changing its location. For best software performance, this folder should be located on a separate local hard drive, different from the one where input/output data are stored.

In the case of the fiducial detection process, a visual representation of the results is also created. For each input photo, an image showing the four detected marks is stored for visual validation. These images are named according to input image.

# 16

## APPENDIX A

### 16.1 Camera Calibration Types

---

Correlator3D™ supports four types of camera calibrations.

#### 1. Digital Sensors

The first calibration type, designed for metric cameras, simply consists of providing the following:

- Image width in pixels
- Image height in pixels
- Pixel size in microns
- Focal length in millimeters
- Principal point coordinates in millimeters

Note that the imagery is assumed to be already corrected for distortion.

#### 2. Digital Sensors with Distortion Table

The second calibration type is meant to specifically support camera systems using a distortion table. The difference in the calibration file is that radial lens distortion is taken into account when processing imagery. The parameter values are thus defined as a look-up table (LUT). These values specify radial distortion as a function of the pixel distance from the image center.

#### 3. Scanned Films

The third calibration type, designed for scanned films, contains additional fields (compared to the digital sensor type) consisting of the coordinates in millimeters of the following:

- Bottom-left fiducial
- Top-right fiducial
- Top-left fiducial
- Bottom-right fiducial

Positions of fiducials and the principal point should be referenced to the principal point of autocollimation as the origin.

#### 4. Polynomial

The fourth calibration type specifically supports camera systems with radial and decentering lens distortion. The parametric distortion model is defined by the following equations, where X and Y are measurements in mm referring to the principal point and  $r = \sqrt{X^2 + Y^2}$ :

$$\begin{aligned}dX &= dX_{\text{radial}} + dX_{\text{decentering}}, \\dY &= dY_{\text{radial}} + dY_{\text{decentering}},\end{aligned}$$

where,

$$\begin{aligned}
dX_{\text{radial}} &= X (K_0 + K_1 * r^2 + K_2 * r^4 + K_3 * r^6 + \dots + K_7 * r^{14}), \\
dY_{\text{radial}} &= Y (K_0 + K_1 * r^2 + K_2 * r^4 + K_3 * r^6 + \dots + K_7 * r^{14}), \\
dX_{\text{decentering}} &= (1 + P_3 * r^2 + P_4 * r^4) * (P_1 * (r^2 + 2 * X^2) + 2 * P_2 * X * Y), \\
dY_{\text{decentering}} &= (1 + P_3 * r^2 + P_4 * r^4) * (P_2 * (r^2 + 2 * Y^2) + 2 * P_1 * X * Y),
\end{aligned}$$

and,

$K_0$  to  $K_7$  are parameters associated with the radial distortion,  
 $P_1$  to  $P_4$  are parameters associated with the decentering distortion.

## 16.2 Tile Definition File

---

A tile definition file can be inputted in Correlator3D™ Mosaic Creation module to define the name, the coordinates and the size of each mosaic tile. A tile is defined by two corners located on the diagonal of its area. Each tile is specified on a separate line containing the following five (5) fields:

- Tile filename
- X coordinate of the first corner defining the tile area
- Y coordinate of the first corner defining the tile area
- X coordinate of the second corner defining the tile area
- Y coordinate of the second corner defining the tile area



*Corners can be specified in any order, as long as they are located on a diagonal.*

Sample:

```

*****
SimActive Tile Definition File
Copyright(c) 2009 SimActive Inc.
All rights reserved.
*****
# Tile Name      First Corner (x,y)    Second Corner (x,y)
TileName_01     446762.0 5032005.0    447170.0 5031653.0
TileName_02     447170.0 5032205.0    447643.0 5031415.0
TileName_03     446862.0 5031653.0    447170.0 5031415.0
TileName_04     447061.0 5031415.0    447351.0 5031120.0
TileName_05     446762.0 5030920.0    447351.0 5031120.0

```

## 16.3 Script Format Description

---

This section describes the operations and parameters available in a Correlator3D™ script.

Script syntax is the following:

```

<OperationName>
{

```

```

    ParameterName ParameterValue
    ParameterName ParameterValue
    ...
    ParameterName ParameterValue
}

```

The script file is case insensitive. This means that “DTMExtraction” and “dtmextraction” are both valid. The name of the operations must appear between ‘<’ and ‘>’ marks and the parameter lists is delimited by a pair of braces (‘{’ and ‘}’). There is no limitation on the number of white spaces (spaces, tabs and new lines) as long as the *ParameterName* and its *ParameterValue* are on the same line. Comments can be added in the file. Each line of comment must be preceded with ‘#’.

*OperationName* can be one of the following:

- AerialTriangulation
- DSMGeneration
- DTMExtraction
- Orthorectification
- MosaicCreation
- 3DModelGeneration
- ExportMosaic
- Export3DModel
- ChangeDetection
- DEMMerging
- DEMTiling
- DEMInspection
- ExportGeoidDEM
- PointCloudColorization
- DEMContourExtraction
- DEMVolumeCalculation
- ShareOnCesium
- ExportMosaicSeamlines
- ImportPointCloud
- PointCloudFiltering

The list of parameters and acceptable values varies according to the operation. For a given operation, the order of the parameters has no importance. The description of each available parameter follows.



*A sample script file is available in the software installation folder under “Sample Files\Script”.*

## Parameters for AerialTriangulation

Parameter name	Type	Description
TiePointExtraction	'On', 'Off'	Indicates if tie point extraction must be performed.
CameraCalibration	'None', 'Constrained', 'Unconstrained'	Indicates the type of camera calibration.
EOAdjustment	'None', 'BoresightCalibration', 'ConstrainedAT', 'UnconstrainedAT', 'Assisted', 'OffsetCorrection'	Indicates the type of EO adjustment.
PerformBoresight	'On', 'Off'	Bound boresight within total uncertainty. Only required if EOAdjustment is 'ConstrainedAT'
ExtractionType	'Standard', 'Exhaustive'	Type of tie point extraction to perform.
ImageFiltering	Float, 'None', 'Automatic'	Indicates the type of image filtering.
InputEO	String	Path to the input interior/exterior orientation file.
GCPFile	String	<b>Optional.</b> Path to the input ground control point file.
InputDEM	String	<b>Optional.</b> Path to the reference DEM. Required for satellite projects.
ReferenceORList	String	<b>Optional.</b> Path to the reference ORI file.
AdjustFocalLength	'On', 'Off'	<b>Optional.</b> Indicates if parameter will be adjusted during bundle adjustment.
AdjustXmm	'On', 'Off'	<b>Optional.</b> Indicates if parameter will be adjusted during bundle adjustment.
AdjustYmm	'On', 'Off'	<b>Optional.</b> Indicates if parameter will be adjusted during bundle adjustment.
AdjustK0	'On', 'Off'	<b>Optional.</b> Indicates if parameter will be adjusted during bundle adjustment for odd/even order polynomial distortion model.
AdjustK1	'On', 'Off'	<b>Optional.</b> Indicates if parameter will be adjusted during bundle adjustment for odd/even order polynomial distortion model.
AdjustK2	'On', 'Off'	<b>Optional.</b> Indicates if parameter will be adjusted during bundle adjustment for odd/even order polynomial distortion model.
AdjustK3	'On', 'Off'	<b>Optional.</b> Indicates if parameter will be adjusted during bundle adjustment for odd/even order polynomial distortion model.
AdjustK4	'On', 'Off'	<b>Optional.</b> Indicates if parameter will be adjusted during bundle adjustment for odd/even order polynomial distortion model.
AdjustK5	'On', 'Off'	<b>Optional.</b> Indicates if parameter will be adjusted during bundle adjustment for odd/even order polynomial distortion model.
AdjustK6	'On', 'Off'	<b>Optional.</b> Indicates if parameter will be adjusted during bundle adjustment for odd/even order polynomial distortion model.
AdjustK7	'On', 'Off'	<b>Optional.</b> Indicates if parameter will be adjusted during bundle adjustment for odd/even order polynomial distortion model.
AdjustP1	'On', 'Off'	<b>Optional.</b> Indicates if parameter will be adjusted during bundle adjustment for odd/even order polynomial distortion model.
AdjustP2	'On', 'Off'	<b>Optional.</b> Indicates if parameter will be adjusted during bundle adjustment for odd/even order polynomial distortion model.
AdjustP3	'On', 'Off'	<b>Optional.</b> Indicates if parameter will be adjusted during bundle adjustment for odd/even order polynomial distortion model.
AdjustP4	'On', 'Off'	<b>Optional.</b> Indicates if parameter will be adjusted during bundle adjustment for odd/even order polynomial distortion model.
AdjustLUT	'On', 'Off'	<b>Optional.</b> Indicates if parameters will be adjusted during bundle adjustment for LUT distortion model.

AdjustX	Float	<b>Optional.</b> Expected uncertainty in parameter to be adjusted during bundle adjustment.
AdjustY	Float	<b>Optional.</b> Expected uncertainty in parameter to be adjusted during bundle adjustment.
AdjustZ	Float	<b>Optional.</b> Expected uncertainty in parameter to be adjusted during bundle adjustment.
AdjustOmega	Float	<b>Optional.</b> Expected uncertainty in parameter to be adjusted during bundle adjustment.
AdjustPhi	Float	<b>Optional.</b> Expected uncertainty in parameter to be adjusted during bundle adjustment.
AdjustKappa	Float	<b>Optional.</b> Expected uncertainty in parameter to be adjusted during bundle adjustment.
AdjustGCPXY	Float	<b>Optional.</b> Expected uncertainty in parameter to be adjusted during bundle adjustment.
AdjustGCPZ	Float	<b>Optional.</b> Expected uncertainty in parameter to be adjusted during bundle adjustment.
AdjustGCPObs	Float	<b>Optional.</b> Expected uncertainty in parameter to be adjusted during bundle adjustment.
ATFolder	String	Path to the AT folder.
OutputDEM	String	Path to the output coarse DEM file.

### Parameters for DSMGeneration

Parameter name	Type	Description
Projection	String	Projection of the DSM in the PROJ.4 format. Required for sensors other than frame-based. Invalid for frame-based sensors since the projection is read from the input EO file.
InputEO	String	Path to the input interior/exterior orientation file.
Resolution	Float, 'Coarse', 'Optimal', 'Maximal'	Required resolution of the resulting DSM.
VertAccuracy	Float, 'Optimal', 'Fast', 'Precise'	Required vertical accuracy of the resulting DSM.
OutputDEM	String	Path to the output DSM file.
3DConstraintFile	String	<b>Optional.</b> Path to the 3D constraint file.
GeneratePointCloud	'On', 'Off'	<b>Optional.</b> Indicates if a point cloud must be generated.
OutputPointCloud	String	Path to the output point cloud file.
MaxNbImages	Integer	<b>Optional.</b> Between 2 and 6. Only if GeneratePointCloud is set to 'On'.
ColorizePointCloud	'On', 'Off'	<b>Optional.</b> Indicates if the point cloud needs to be colorized.
NbBands	Integer, 'Automatic',	<b>Optional.</b> Number of bands to be exported to the texture file. Must be commented out if TextureFormat is set to 'None'.
BandAssign	'OutputBandX = Y'	<b>Optional.</b> Required when NbBands is set to an integer. X corresponds to the output band number, and Y to the imagery band number. The band name can also be used for multispectral projects where each band has a name.
BandAssign	'OutputBandY = Z'	...
BandAssign	'OutputBandZ = X'	...

### Parameters for DTMExtraction

Parameter name	Type	Description
InputDEM	String	Path to the input DEM file.
3DConstraintFile	String	<b>Optional.</b> Path to the 3D constraint file.
ConstraintType	'Exclusion', 'Elevation'	<b>Optional.</b> Type of constraint to be used.
DSMFeatures	String	<b>Optional.</b> Path to the output DEM.
OutputDEM	String	Path to the output DTM file.

### Parameters for Orthorectification

Parameter name	Type	Description
InputDEM	String	Path to the DEM file.
InputEO	String	Path to the input interior/exterior orientation file.
DSMBased	'On', 'Off'	Parameter used to generate true orthos from a DSM.
3DConstraintFile	String	<b>Optional.</b> Parameter used to generate true orthos using a 3D constraint file.
OutputORIFolder	String	Path to the output folder.
Resolution	Float, 'Optimal', 'Coarse'	Required resolution of the orthorectified images.
Overlap	Integer, 'Optimal', 'Maximal'	Required overlap between orthorectified images. Must be commented out if CropWidth and CropHeight are specified.
BoundLeft	Integer	Crop percentage (0 to 99). Must be commented out if Overlap is specified.
BoundRight	Integer	Crop percentage (0 to 99). Must be commented out if Overlap is specified.
BoundTop	Integer	Crop percentage (0 to 99). Must be commented out if Overlap is specified.
BoundBottom	Integer	Crop percentage (0 to 99). Must be commented out if Overlap is specified.
UseSunSensor	'On', 'Off'	<b>Optional.</b> Indicates is sun sensor must be used for reflectance.
PanelFile	String	<b>Optional.</b> Path to the calibrated reflectance panel file.
OutputFormat	'GeoTIFF', 'TFW'	Output format of the orthorectified images.
TiledTiff	'Tiled', 'Untiled'	Indicates if the orthorectified images must be tiled or untiled.
Overviews	'On', 'Off'	Indicates if the orthorectified images must be generated with overviews.
JPEGInTIFF	'On', 'Off'	Indicates if JPEG compression must be used in TIFFs.
BitDepth	'8', '16' or '32'	<b>Optional.</b> For 16-bit imagery, BitDepth can be set to 8 to downscale the bit depth. Otherwise, if specified, it must match the bit depth of the input imagery.

### Parameters for MosaicCreation

Parameter name	Type	Description
InputORIList	String	The default file name is the name of the IEO file used to orthorectify the images.
MosaicArea	String	<b>Optional.</b> Path to the tile definition or vector file.
OutputFolder	String	Path to the output folder.
MosaicName	String	Name of the mosaic.
Feathering	Integer	<b>Optional</b> parameter. Default value is 37.
MinNumBlocks	Integer	<b>Optional</b> parameter. Default value is 1.
ColorBalancing	'On', 'Off'	Indicates if color balancing must be applied.
OptimizeViewAngle	'On', 'Off'	Indicates if nadir optimization must be applied.
ExclusionZone	String	<b>Optional.</b> Path to the vector file. The exclusion zone file is only considered when color balancing is on.
InputDEM	String	<b>Optional.</b> Path to the DSM that constrains the seamlines.

### Parameters for 3DModelGeneration

Parameter name	Type	Description
InputDEM	String	Path to the DEM file. Must be commented out if Input3DModel is specified.
Input3DModel	String	Path to the 3D model file. Must be commented out if InputDEM is specified.
InputEO	String	<b>Optional.</b> Path to the input interior/exterior orientation file. Only required if GenerateTexture is 'On'.
Output3DModel	String	Path to the output 3D model file.
GenerateTexture	'On', 'Off'	Indicates if texture must be generated.
JPEGInTIFF	'On', 'Off'	<b>Optional.</b> Indicates if JPEG compression must be used in TIFFs.
BitDepth	'8', '16' or '32'	<b>Optional.</b> For 16-bit imagery, BitDepth can be set to 8 to downscale the bit depth. Otherwise, if specified, it must match the bit depth of the input imagery.

ModelSize	Integer, 'Coarse', 'Optimal', 'Maximal'	Required size of the 3D model. Numerical values must be specified in megabytes (MB).
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### Parameters for ExportMosaic

Parameter name	Type	Description
BlockDefFile	String	Path to the mosaic definition file.
MosaicType	'Standard', 'Reflectance', 'NDVI', 'BNDVI', 'GNDVI', 'LCI', 'NDRE', 'SIPI', 'SIPI2', 'ARVI', 'GCL', 'NBR', 'Custom'	Type of the mosaic to be created.
NbBands	Integer, 'Automatic'	<b>Optional.</b> Number of bands to be exported. Required when 'MosaicType' is set to 'Standard' or 'Reflectance'.
BandAssign	'OutputBandX = Y'	<b>Optional.</b> Required when 'NbBands' is set to an integer. X corresponds to the index of the output band and Y to the index of the input band. Must be defined for each band (NbBands). For predefined mosaic types, supported values for 'BandAssign' include: Red, Green, Blue, RedEdge, NIR, and SWIR. Example: BandAssign       Red = 2 The band name can also be used for multispectral projects where each band has a name. BandAssign       OutputBand4 = RedEdge
IndexFormula	String	<b>Optional.</b> Only required if 'MosaicType' is set to 'Custom'. Defines any operation between user-defined variables including addition, subtraction, multiplication, division, parenthesis, and use of constants. Consequently, 'BandAssign' must be defined for all variables. Example:  IndexFormula     ((Blue - Red) / (Green + Red)) BandAssign       Blue = 1 BandAssign       Red = 3 BandAssign       Green = 2
Colors	'On', 'Off'	<b>Optional.</b> Only required if 'MosaicType' is not set to 'Standard' or 'Reflectance'. 'On' will output an index map following the specified color map. 'Off' will output the floating point result of the index.
UndefValue	Float	<b>Optional.</b> Value to be used for undefined pixels. Required when 'Colors' is set to 'Off'.
ColorMap	'Beige to Dark Green', 'Dark Blue to Dark Green', 'DEM Color Style', 'Grayscale', 'Red to Blue'	<b>Optional*.</b> The color map to be used.
InvertColorMap	'On', 'Off'	<b>Optional*.</b> Invert the color map.
MinimumThreshold	Float, 'Optimal'	<b>Optional*.</b> Minimum bound of the NDVI index.
MaximumThreshold	Float, 'Optimal'	<b>Optional*.</b> Maximum bound of the NDVI index.
ClassCount	Integer	<b>Optional*.</b> Number of classes for the index. If omitted, the mapping is continuous.
OutputFolder	String	Path to the output folder.
ExportArea	String	<b>Optional.</b> Path to the area file.
TileDefFile	String	<b>Optional**.</b> Path to the tile definition file.
MosaicName	String	<b>Optional**.</b> Name of the output mosaic.
TileWidth	Integer	<b>Optional**.</b> Tile width in pixels. Must be commented out if TileDefFile is specified or SingleTile is 'On'.
TileHeight	Integer	<b>Optional**.</b> Tile height in pixels. Must be commented out if TileDefFile is specified or SingleTile is 'On'.
SingleTile	'On', 'Off'	<b>Optional**.</b> Indicates if the mosaic must be exported to a single tile. Must be commented out if TileDefFile is specified.
OutputFormat	'GeoTIFF', 'TFW'	Output format of the mosaic tiles.

TiledTiff	'Tiled', 'Untiled'	Indicates if the orthorectified images must be tiled or untiled.
Overviews	'On', 'Off'	Indicates if the orthorectified images must be generated with overviews.
JPEGInTIFF	'On', 'Off', 'JPEG8'	Indicates if JPEG compression must be used in TIFFs. 'JPEG8' is used to convert imagery with more than 8 bits per band to 8-bit JPEG-compressed TIFFs.

\*Must be defined when mosaic type is set to NDVI.

\*\*Either TileDefFile or MosaicName, TileWidth and TileHeight, or SingleTile can be specified.

### Parameters for Export3DModel

Parameter name	Type	Description
Input3DModel	String	Path to the 3D model file to be exported.
TextureFormat	'TIFF', 'JPG' or 'None'	The format of the texture to be exported.
NbBands	Integer, 'Automatic',	Number of bands to be exported to the texture file. Must be commented out if TextureFormat is set to 'None'.
BandAssign	'OutputBandX = Y'	<b>Optional.</b> Required when NbBands is set to an integer. X corresponds to the output band number, and Y to the imagery band number. The band name can also be used for multispectral projects where each band has a name.
BandAssign	'OutputBandY = Z'	...
BandAssign	'OutputBandZ = X'	...
...	...	...
Output3DModel	String	Path to the exported 3D model file.

### Parameters for ChangeDetection

Parameter name	Type	Description
ReferenceDEM	String	Path to the DEM file before the changes.
ComparisonDEM	String	Path to the DEM file after the changes.
MinimumThreshold	Float	Minimum detection threshold (in model units).
MaximumThreshold	Float	Maximum detection threshold (in model units).
OutputDEM	String	Path to the output DEM file.
BlockDefFile	String	<b>Optional.</b> Path to the block definition file.
OutputFolder	String	<b>Optional.</b> Path to the mosaic output folder.

### Parameters for DEMMerging

Parameter name	Type	Description
InputDEM	String	Path to the input DEM file.
InputDEM	String	
InputDEM	String	
...	...	...
FillGaps	'On', 'Off'	Indicates if the gaps in the resulting DEM must be filled.
OutputDEM	String	Path to the output DEM file.

### Parameters for DEMTiling

Parameter name	Type	Description
InputDEM	String	Path to the input DEM file.
OutputFolder	String	Path to the mosaic output folder.
TileDefFile	String	<b>Optional*</b> . Path to the tile definition file.
DEMName	String	<b>Optional*</b> . Name of the output mosaic.
TileWidth	Integer	<b>Optional*</b> . Tile width in pixels
TileHeight	Integer	<b>Optional*</b> . Tile height in pixels
OutputFormat	'GeoTIFF', 'AsciiGrid', 'SMF2Format', 'SMFFormat', 'Shapefile', 'LIDARLAS', 'LIDARLAZ'	Format of the output DEM tiles.

\*Either TileDefFile or DEMName, TileWidth and TileHeight can be specified.

### Parameters for DEMInspection

Parameter name	Type	Description
InputDEM	String	Path to the input DEM file.
ReferenceData	String	Path to the reference data file.
OutputFile	String	Path to the output statistics file.

### Parameters for ExportGeoidDEM

Parameter name	Type	Description
InputDEM	String	Path to the input DEM file.
GeoidFile	String	Path to the geoid file.
OutputDEM	String	Path to the output DEM file.

### Parameters for PointCloudColorization

Parameter name	Type	Description
InputPointCloud	String	Path to the input point cloud file.
BlockDefFile	String	Path to the mosaic file.
OutputPointCloud	String	Path to the output point cloud file.
NbBands	Integer, 'Automatic'	<b>Optional.</b> Output bands need to be provided if and only if "NbBands" is set to a numerical value. In this case, the number of provided "BandAssign" needs to match the number of bands "NbBands".
BandAssign	'OutputBandX = Y'	<b>Optional.</b> X corresponds to the output band number, and Y to the imagery band number. The band name can also be used for multispectral projects where each band has a name.
BandAssign	'OutputBandY = Z'	...
BandAssign	'OutputBandZ = X'	...

### Parameters for DEMContourExtraction

Parameter name	Type	Description
InputDEM	String	Path to the input DEM file.
Interval	Float	Interval between contours (in model units).
Offset	Float	Offset from zero relative to which to interpret intervals (in model units).
ElevationAttribute	String	<b>Optional*</b> . Name of the attribute containing the elevation.
OutputFile	String	Path to the output contour file.

### Parameters for DEMVolumeCalculation

Parameter name	Type	Description
InputDEM	String	Path to the input DEM file.
InputArea	String	Path to the area file.
ReferenceType	'InterpolateDEM', 'InterpolatePoly', 'FixedElev', 'Dig', 'Fill', 'RefDEM'	The type of reference to be used to calculate volume.
Offset	Float	<b>Optional.</b> Only used with 'Dig' and 'Fill' options.
Elevation	Float	<b>Optional.</b> Only used with 'FixedElev' option.
ReferenceDEM	String	<b>Optional.</b> Only used with 'RefDEM' option.
OutputFile	String	Path to the output statistics file.

### Parameters for ShareOnCesium

Parameter name	Type	Description
ProfileName	String	Name of the Cesium profile.
ProjectName	String	Name of the project.
Projection	String	<b>Optional.</b> Projection of the project in the PROJ.4 format. Required for projects for which it was not previously defined.
InputPointCloud	String	<b>Optional.</b> Path to the point cloud file.
InputDEM	String	<b>Optional.</b> Path to the DEM file.

BlockDefFile	String	<b>Optional.</b> Path to the mosaic file.
Input3DModel	String	<b>Optional.</b> Path to the 3D model file.
NbBands	Integer	Number of bands to be exported to the texture file. <b>The only accepted value is 3.</b>
BandAssign	'OutputBandX = Y'	X corresponds to the output band number, and Y to the imagery band number. This parameter must be specified. The band name can also be used for multispectral projects where each band has a name.
BandAssign	'OutputBandY = Z'	...
BandAssign	'OutputBandZ = X'	...

#### Parameters for ExportMosaicSeamlines

Parameter name	Type	Description
BlockDefFile	String	Path to the mosaic definition file.
OutputFile	String	Path to the output seamline file.

#### Parameters for ImportPointCloud

Parameter name	Type	Description
InputPointCloud	String	Path to the input point cloud file.
InputPointCloud	String	
InputPointCloud	String	
...	...	...
OutputDEM	String	Path to the output DEM file.
OutputFolder	String	Path to the output folder.
MosaicName	String	Name of the mosaic.

#### Parameters for PointCloudFiltering

Parameter name	Type	Description
InputPointCloud	String	Path to the input point cloud file.
OutputPointCloud	String	Path to the output point cloud file.
NumberOfObservations	2 = 'On', 'Off'	The number of observations ranges from 2 up to 6. At least one "NumberOfObservations" must be set to 'Off'. If not specified, the number of observations is set to 'On' by default.
NumberOfObservations	3 = 'On', 'Off'	
NumberOfObservations	4 = 'On', 'Off'	
NumberOfObservations	5 = 'On', 'Off'	
NumberOfObservations	6 = 'On', 'Off'	